EN25P16
16 Mbit Uniform Sector, Serial Flash Memory

FEATURES

- Single power supply operation
  - Full voltage range: 2.7-3.6 volt
- 16 Mbit Serial Flash
  - 16 M-bit/2048 K-byte/8192 pages
  - 256 bytes per programmable page
- High performance
  - 75MHz clock rate
- Low power consumption
  - 5 mA typical active current
  - 1 μA typical power down current
- Uniform Sector Architecture:
  - Thirty two 64-Kbyte sectors
- Software and Hardware Write Protection:
  - Write Protect all or portion of memory via software
  - Enable/Disable protection with WP# pin
- High performance program/erase speed
  - Byte program time: 7μs typical
  - Page program time: 1.5ms typical
  - Sector erase time: 800ms typical
  - Chip erase time: 18 Seconds typical
- Minimum 100K endurance cycle
- Package Options
  - 8 pins SOP 200mil body width
  - 8 contact VDFN
  - 16 pin SOP 300mil body width
  - All Pb-free packages are RoHS compliant
- Commercial and industrial temperature Range

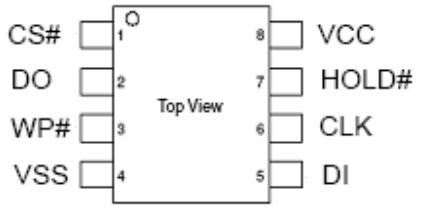
GENERAL DESCRIPTION

The EN25P16 is a 16M-bit (2048K-byte) Serial Flash memory, with advanced write protection mechanisms, accessed by a high speed SPI-compatible bus. The memory can be programmed 1 to 256 bytes at a time, using the Page Program instruction.

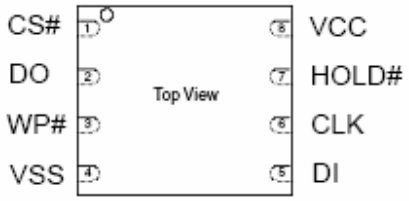
The EN25P16 is designed to allow either single Sector at a time or full chip erase operation. The EN25P16 can be configured to protect part of the memory as the software protected mode. The device can sustain a minimum of 100K program/erase cycles on each sector.

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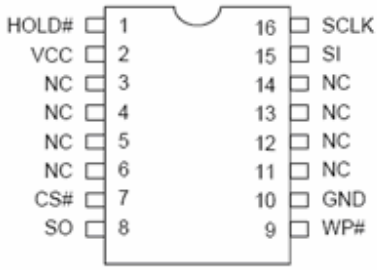
Figure.1 CONNECTION DIAGRAMS



8 - LEAD SOP

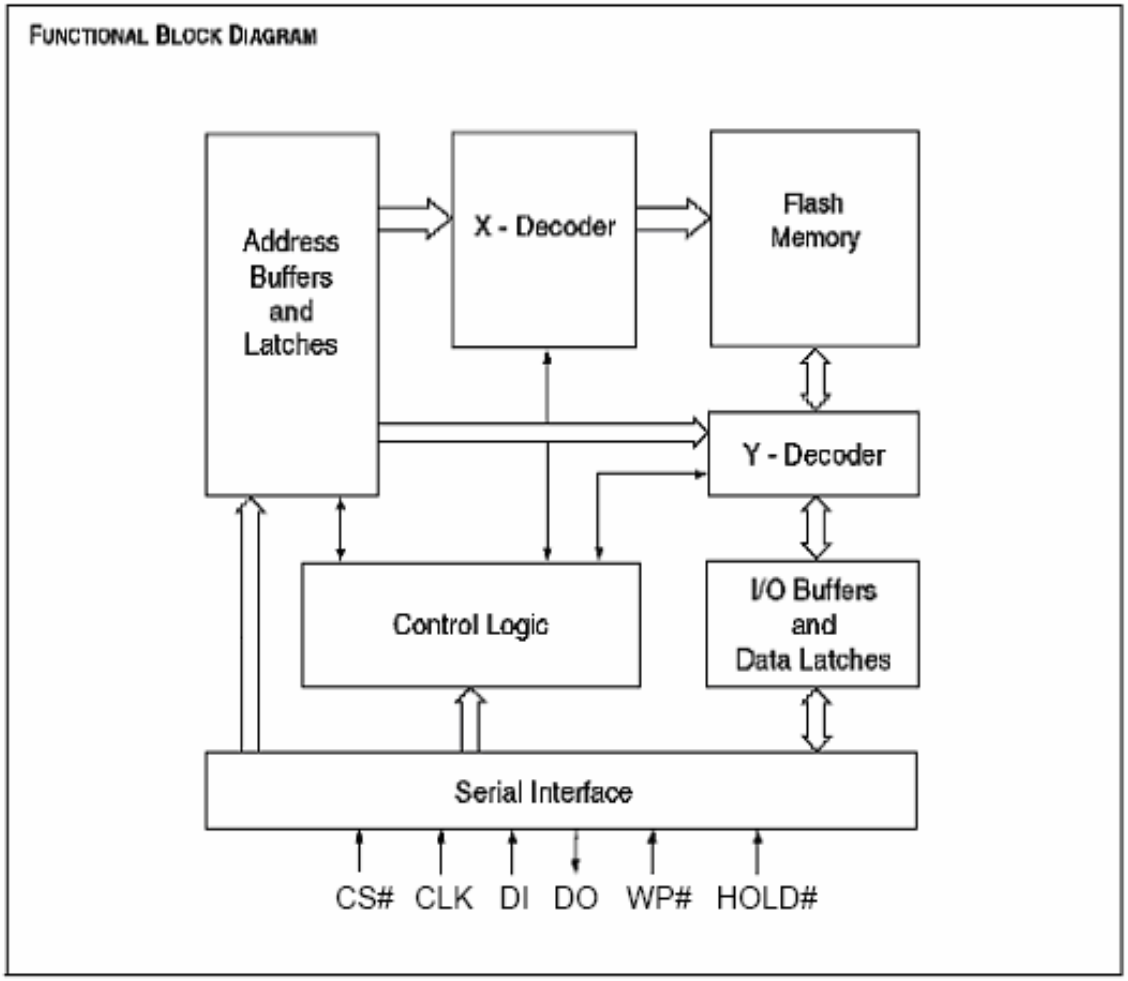


8 - CONTACT VDFN



16 - LEAD SOP

Figure 2. BLOCK DIAGRAM



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SIGNAL DESCRIPTION

Serial Data Input (DI)
The SPI Serial Data Input (DI) pin provides a means for instructions, addresses and data to be serially written to (shifted into) the device. Data is latched on the rising edge of the Serial Clock (CLK) input pin.

Serial Data Output (DO)
The SPI Serial Data Output (DO) pin provides a means for data and status to be serially read from (shifted out of) the device. Data is shifted out on the falling edge of the Serial Clock (CLK) input pin.

Serial Clock (CLK)
The SPI Serial Clock Input (CLK) pin provides the timing for serial input and output operations. ("See SPI Mode")

Chip Select (CS#)
The SPI Chip Select (CS#) pin enables and disables device operation. When CS# is high the device is deselected and the Serial Data Output (DO) pin is at high impedance. When deselected, the devices power consumption will be at standby levels unless an internal erase, program or status register cycle is in progress. When CS# is brought low the device will be selected, power consumption will increase to active levels and instructions can be written to and data read from the device. After power-up, CS# must transition from high to low before a new instruction will be accepted.

Hold (HOLD#)
The HOLD pin allows the device to be paused while it is actively selected. When HOLD is brought low, while CS# is low, the DO pin will be at high impedance and signals on the DI and CLK pins will be ignored (don't care). The hold function can be useful when multiple devices are sharing the same SPI signals.

Write Protect (WP#)
The Write Protect (WP#) pin can be used to prevent the Status Register from being written. Used in conjunction with the Status Register's Block Protect (BP0, BP1and BP2) bits and Status Register Protect (SRP) bits, a portion or the entire memory array can be hardware protected.

Table 1. PIN Names

Symbol	Pin Name
CLK	Serial Clock Input
DI	Serial Data Input
DO	Serial Data Output
CS#	Chip Enable
WP#	Write Protect
HOLD#	Hold Input
Vcc	Supply Voltage (2.7-3.6V)
Vss	Ground

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MEMORY ORGANIZATION

The memory is organized as:

- 2,097,152 bytes
- Uniform Sector Architecture
  Thirty two 64-Kbyte sectors
- 8192 pages (256 bytes each)

Each page can be individually programmed (bits are programmed from 1 to 0). The device is Sector or Bulk Erasable but not Page Erasable.

Table 2. Block Sector Architecture

Sector	SECTOR SIZE (KByte)	Address range
31	64	1F0000h – 1FFFFFh
30	64	1E0000h – 1EFFFFh
29	64	1D0000h – 1DFFFFh
28	64	1C0000h – 1CFFFFh
27	64	1B0000h – 1BFFFFh
26	64	1A0000h – 1AFFFFh
25	64	190000h – 19FFFFh
24	64	180000h – 18FFFFh
23	64	170000h – 17FFFFh
22	64	160000h – 16FFFFh
21	64	150000h – 15FFFFh
20	64	140000h – 14FFFFh
19	64	130000h – 13FFFFh
18	64	120000h – 12FFFFh
17	64	110000h – 11FFFFh
16	64	100000h – 10FFFFh
15	64	0F0000h – 0FFFFFh
14	64	0E0000h – 0EFFFFh
13	64	0D0000h – 0DFFFFh
12	64	0C0000h – 0CFFFFh
11	64	0B0000h – 0BFFFFh
10	64	0A0000h – 0AFFFFh
9	64	090000h – 09FFFFh
8	64	080000h – 08FFFFh
7	64	070000h – 07FFFFh
6	64	060000h – 06FFFFh
5	64	050000h – 05FFFFh
4	64	040000h – 04FFFFh
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1	64	010000h – 01FFFFh
0	64	000000h – 00FFFFh

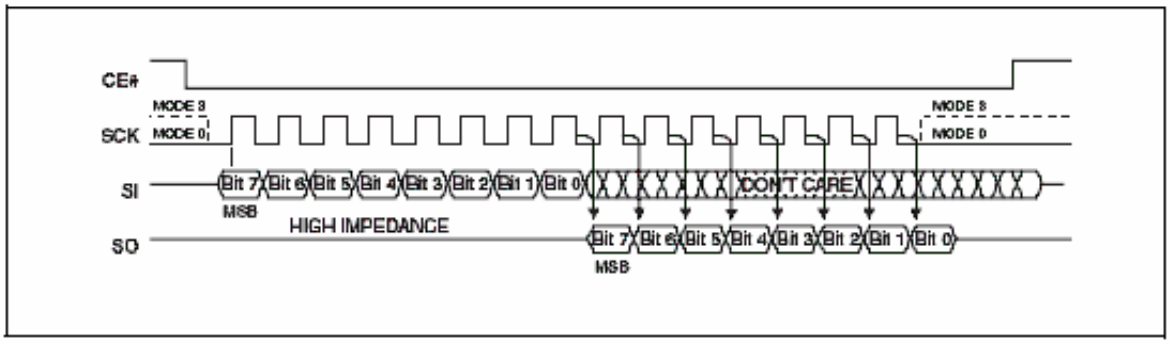
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OPERATING FEATURES

SPI Modes

The EN25P16 is accessed through an SPI compatible bus consisting of four signals: Serial Clock (CLK), Chip Select (CS#), Serial Data Input (DI) and Serial Data Output (DO). Both SPI bus operation Modes 0 (0,0) and 3 (1,1) are supported. The primary difference between Mode 0 and Mode 3, as shown in Figure 3, concerns the normal state of the SCK signal when the SPI bus master is in standby and data is not being transferred to the Serial Flash. For Mode 0 the SCK signal is normally low. For Mode 3 the SCK signal is normally high. In either case data input on the DI pin is sampled on the rising edge of the SCK. Data output on the DO pin is clocked out on the falling edge of SCK.

Figure 3. SPI Modes



Page Programming

To program one data byte, two instructions are required: Write Enable (WREN), which is one byte, and a Page Program (PP) sequence, which consists of four bytes plus data. This is followed by the internal Program cycle (of duration tPP).

To spread this overhead, the Page Program (PP) instruction allows up to 256 bytes to be programmed at a time (changing bits from 1 to 0), provided that they lie in consecutive addresses on the same page of memory.

Sector Erase and Bulk Erase

The Page Program (PP) instruction allows bits to be reset from 1 to 0. Before this can be applied, the bytes of memory need to have been erased to all 1s (FFh). This can be achieved either a sector at a time, using the Sector Erase (SE) instruction, or throughout the entire memory, using the Bulk Erase (BE) instruction. This starts an internal Erase cycle (of duration tSE or tBE). The Erase instruction must be preceded by a Write Enable (WREN) instruction.

Polling During a Write, Program or Erase Cycle

A further improvement in the time to Write Status Register (WRSR), Program (PP) or Erase (SE or BE) can be achieved by not waiting for the worst case delay (tW, tPP, tSE, or tBE). The Write In Progress (WIP) bit is provided in the Status Register so that the application program can monitor its value, polling it to establish when the previous Write cycle, Program cycle or Erase cycle is complete.

Active Power, Stand-by Power and Deep Power-Down Modes

When Chip Select (CS#) is Low, the device is enabled, and in the Active Power mode. When Chip Select (CS#) is High, the device is disabled, but could remain in the Active Power mode until all internal cycles have completed (Program, Erase, Write Status Register). The device then goes in to the Stand-by Power mode. The device consumption drops to I_{CC1}.

The Deep Power-down mode is entered when the specific instruction (the Enter Deep Power-down Mode (DP) instruction) is executed. The device consumption drops further to I_{CC2}. The device remains in this mode until another specific instruction (the Release from Deep Power-down Mode and Read Device ID (RDI) instruction) is executed.

All other instructions are ignored while the device is in the Deep Power-down mode. This can be used as an extra software protection mechanism, when the device is not in active use, to protect the device from inadvertent Write, Program or Erase instructions.

Status Register. The Status Register contains a number of status and control bits that can be read or set (as appropriate) by specific instructions.

BUSY bit. The BUSY bit indicates whether the memory is busy with a Write Status Register, Program or Erase cycle.

WEL bit. The Write Enable Latch (WEL) bit indicates the status of the internal Write Enable Latch.

BP2, BP1, BP0 bits. The Block Protect (BP2, BP1, BP0) bits are non-volatile. They define the size of the area to be software protected against Program and Erase instructions.

SRP bit. The Status Register Protect (SRP) bit is operated in conjunction with the Write Protect (WP#) signal. The Status Register Protect (SRP) bit and Write Protect (WP#) signal allow the device to be put in the Hardware Protected mode. In this mode, the non-volatile bits of the Status Register (SRP, BP2, BP1, BP0) become read-only bits.

Write Protection

Applications that use non-volatile memory must take into consideration the possibility of noise and other adverse system conditions that may compromise data integrity. To address this concern the EN25P16 provides the following data protection mechanisms:

- Power-On Reset and an internal timer (t_{PUW}) can provide protection against inadvertent changes while the power supply is outside the operating specification.
- Program, Erase and Write Status Register instructions are checked that they consist of a number of clock pulses that is a multiple of eight, before they are accepted for execution.
- All instructions that modify data must be preceded by a Write Enable (WREN) instruction to set the Write Enable Latch (WEL) bit . This bit is returned to its reset state by the following events:
  - Power-up
  - Write Disable (WRDI) instruction completion or Write Status Register (WRSR) instruction completion or Page Program (PP) instruction completion or Sector Erase (SE)instruction completion or Bulk Erase (BE) instruction completion or
- The Block Protect (BP2, BP1, BP0) bits allow part of the memory to be configured as read-only. This is the Software Protected Mode (SPM).
- The Write Protect (WP#) signal allows the Block Protect (BP2, BP1, BP0) bits and Status Register Protect (SRP) bit to be protected. This is the Hardware Protected Mode (HPM).
- In addition to the low power consumption feature, the Deep Power-down mode offers extra software protection from inadvertent Write, Program and Erase instructions, as all instructions are ignored except one particular instruction (the Release from Deep Power-down instruction).

Table 3. Protected Area Sizes Sector Organization

Status Register Content			Memory Content			
BP2 Bit	BP1 Bit	BP0 Bit	Protect Sectors	Addresses	Density(KB)	Portion
1	1	1	All	000000h-1FFFFFh	2048KB	All
1	1	0	All	000000h-1FFFFFh	2048KB	All
1	0	1	Sector 16 to 31	100000h-1FFFFFh	1024KB	Upper 1/2
1	0	0	Sector 24 to 31	180000h-1FFFFFh	512KB	Upper 1/4
0	1	1	Sector 28 to 31	1C0000h-1FFFFFh	256KB	Upper 1/8
0	1	0	Sector 30 to 31	1E0000h-1FFFFFh	128KB	Upper 1/16
0	0	1	Sector 31	1F0000h-1FFFFFh	64KB	Upper 1/32
0	0	0	None	None	None	None

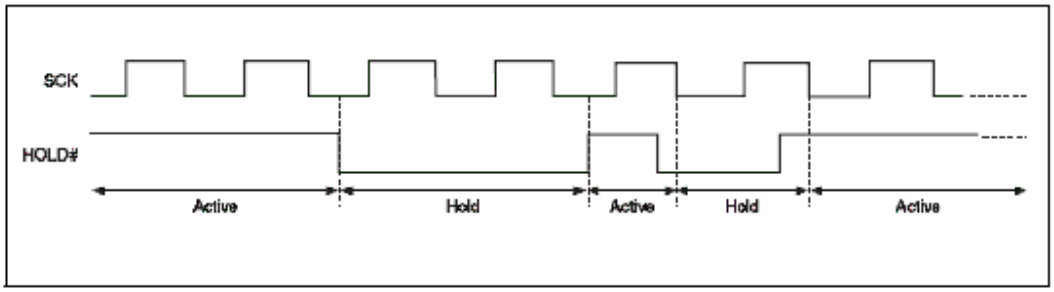
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Hold Function

The Hold (HOLD) signal is used to pause any serial communications with the device without resetting the clocking sequence. However, taking this signal Low does not terminate any Write Status Register, Program or Erase cycle that is currently in progress.
To enter the Hold condition, the device must be selected, with Chip Select (CS#) Low. The Hold condition starts on the falling edge of the Hold (HOLD) signal, provided that this coincides with Serial Clock (CLK) being Low (as shown in Figure 4.).
The Hold condition ends on the rising edge of the Hold (HOLD) signal, provided that this coincides with Serial Clock (CLK) being Low.
If the falling edge does not coincide with Serial Clock (CLK) being Low, the Hold condition starts after Serial Clock (CLK) next goes Low. Similarly, if the rising edge does not coincide with Serial Clock (CLK) being Low, the Hold condition ends after Serial Clock (CLK) next goes Low. (This is shown in Figure 4.).

During the Hold condition, the Serial Data Output (DO) is high impedance, and Serial Data Input (DI) and Serial Clock (CLK) are Don't Care.
Normally, the device is kept selected, with Chip Select (CS#) driven Low, for the whole duration of the Hold condition. This is to ensure that the state of the internal logic remains unchanged from the moment of entering the Hold condition.
If Chip Select (CS#) goes High while the device is in the Hold condition, this has the effect of resetting the internal logic of the device. To restart communication with the device, it is necessary to drive Hold (HOLD) High, and then to drive Chip Select (CS#) Low. This prevents the device from going back to the Hold condition.

Figure 4. Hold Condition Waveform



INSTRUCTIONS

All instructions, addresses and data are shifted in and out of the device, most significant bit first. Serial Data Input (DI) is sampled on the first rising edge of Serial Clock (CLK) after Chip Select (CS#) is driven Low. Then, the one-byte instruction code must be shifted in to the device, most significant bit first, on Serial Data Input (DI), each bit being latched on the rising edges of Serial Clock (CLK).

The instruction set is listed in Table 4. Every instruction sequence starts with a one-byte instruction code. Depending on the instruction, this might be followed by address bytes, or by data bytes, or by both or none. Chip Select (CS#) must be driven High after the last bit of the instruction sequence has been shifted in. In the case of a Read Data Bytes (READ), Read Data Bytes at Higher Speed (Fast_Read), Read Status Register (RDSR) or Release from Deep Power-down, and Read Device ID (RDI) instruction, the shifted-in instruction sequence is followed by a data-out sequence. Chip Select (CS#) can be driven High after any bit of the data-out sequence is being shifted out.

In the case of a Page Program (PP), Sector Erase (SE), Bulk Erase (BE), Write Status Register (WRSR), Write Enable (WREN), Write Disable (WRDI) or Deep Power-down (DP) instruction, Chip Select (CS#) must be driven High exactly at a byte boundary, otherwise the instruction is rejected, and is not executed. That is, Chip Select (CS#) must driven High when the number of clock pulses after Chip Select (CS#) being driven Low is an exact multiple of eight. For Page Program, if at any time the input byte is not a full byte, nothing will happen and WEL will not be reset.

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In the case of multi-byte commands of Page Program (PP), and Release from Deep Power Down (RES) minimum number of bytes specified has to be given, without which, the command will be ignored.

In the case of Page Program, if the number of byte after the command is less than 4 (at least 1 data byte), it will be ignored too. In the case of SE, exact 24-bit address is a must, any less or more will cause the command to be ignored.

All attempts to access the memory array during a Write Status Register cycle, Program cycle or Erase cycle are ignored, and the internal Write Status Register cycle, Program cycle or Erase cycle continues unaffected.

Table 4. Instruction Set

Instruction Name	Byte 1 Code	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	n-Bytes
Write Enable	06h						
Write Disable	04h						
Read Status Register	05h	(S7-S0)(1)					continuous (2)
Write Status Register	01h	S7-S0					
Read Data	03h	A23-A16	A15-A8	A7-A0	(D7-D0)	(Next byte)	continuous
Fast Read	0Bh	A23-A16	A15-A8	A7-A0	dummy	(D7-D0)	(Next Byte) continuous
Page Program	02h	A23-A16	A15-A8	A7-A0	D7-D0	(Next byte)	continuous
Sector Erase	D8h	A23-A16	A15-A8	A7-A0			
Bulk Erase	C7h						
Deep Power-down	B9h						
Release from Deep Power-down, and read Device ID	ABh	dummy	dummy	dummy	(ID7-ID0)		(4)
Release from Deep Power-down							
Manufacturer/ Device ID	90h	dummy	dummy	00h(5)	(M7-M0)	(ID7-ID0)	
Read Identification	9Fh	(M7-M0)	(ID15-ID8)	(ID7-ID0)			

Notes:
1. Data bytes are shifted with Most Significant Bit first. Byte fields with data in parenthesis "( )" indicate data being read from the device on the DO pin.
2. The Status Register contents will repeat continuously until CS# terminate the instruction.
3. All sectors may use any address within the sector.
4. The Device ID will repeat continuously until CS# terminate the instruction.
5. The Manufacturer ID and Device ID bytes will repeat continuously until CS# terminate the instruction. 00h on Byte 4 starts with MID and alternate with DID, 01h on Byte 4 starts with DID and alternate with MID.

Table 5. Manufacturer and Device Identification

OP Code	(M7-M0)	(ID15-ID0)	(ID7-ID0)
ABh			14h
90h	1Ch		14h
9Fh	1Ch	2015h	

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Write Enable (WREN) (06h)

The Write Enable (WREN) instruction (Figure 5) sets the Write Enable Latch (WEL) bit. The Write Enable Latch (WEL) bit must be set prior to every Page Program (PP), Sector Erase (SE), Bulk Erase (BE) and Write Status Register (WRSR) instruction.

The Write Enable (WREN) instruction is entered by driving Chip Select (CS#) Low, sending the instruction code, and then driving Chip Select (CS#) High.

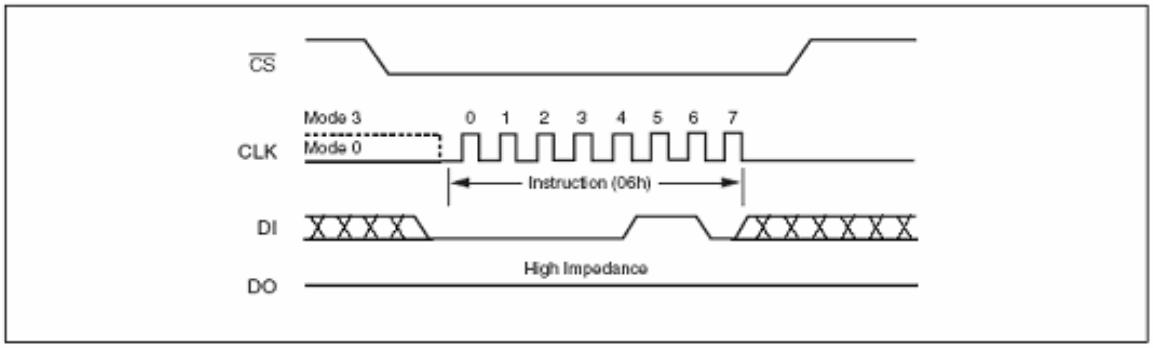


Figure 5. Write Enable Instruction Sequence Diagram

Write Disable (WRDI) (04h)

The Write Disable instruction (Figure 6) resets the Write Enable Latch (WEL) bit in the Status Register to a 0. The Write Disable instruction is entered by driving Chip Select (CS#) low, shifting the instruction code "04h" into the DI pin and then driving Chip Select (CS#) high. Note that the WEL bit is automatically reset after Power-up and upon completion of the Write Status Register, Page Program, Sector Erase, and Bulk Erase instructions.

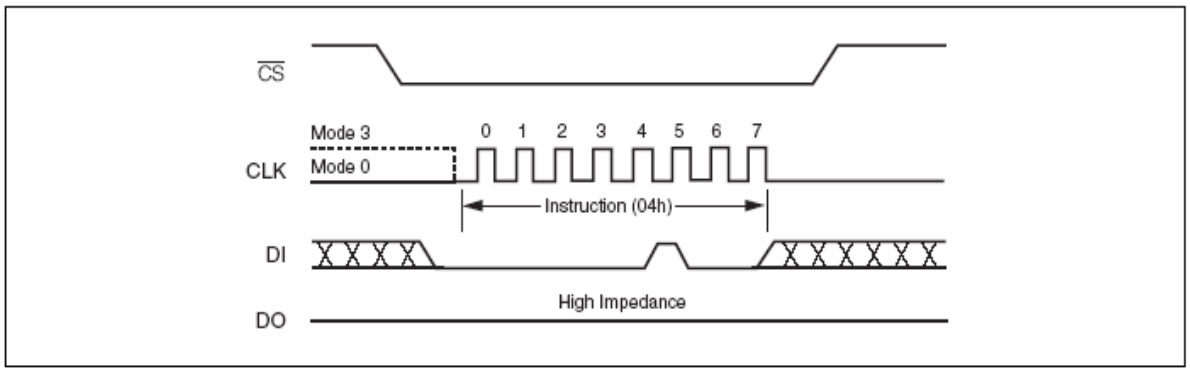


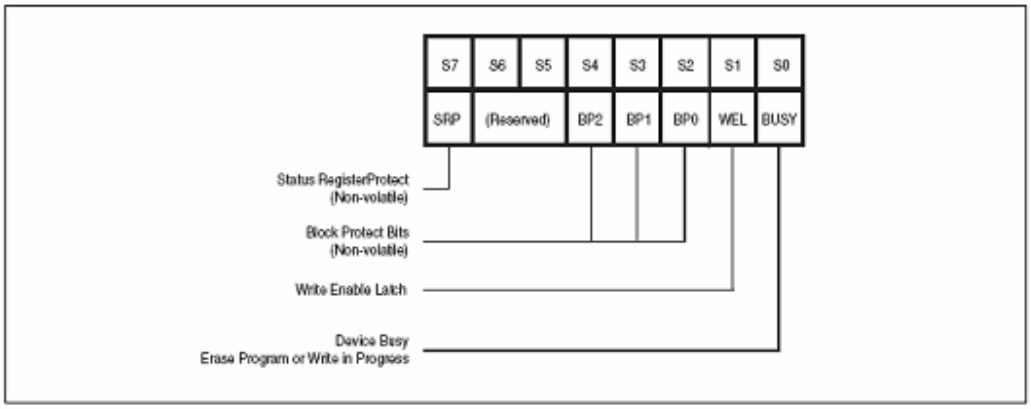
Figure 6. Write Disable Instruction Sequence Diagram

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Read Status Register (RDSR) (05h)

The Read Status Register (RDSR) instruction allows the Status Register to be read. The Status Register may be read at any time, even while a Program, Erase or Write Status Register cycle is in progress. When one of these cycles is in progress, it is recommended to check the Write In Progress (WIP) bit before sending a new instruction to the device. It is also possible to read the Status Register continuously, as shown in Figure 7.

Table 6. Status Register Bit Locations



The status and control bits of the Status Register are as follows:
BUSY bit. The BUSY bit indicates whether the memory is busy with a Write Status Register, Program or Erase cycle. When set to 1, such a cycle is in progress, when reset to 0 no such cycle is in progress.

WEL bit. The Write Enable Latch (WEL) bit indicates the status of the internal Write Enable Latch. When set to 1 the internal Write Enable Latch is set, when set to 0 the internal Write Enable Latch is reset and no Write Status Register, Program or Erase instruction is accepted.

BP2, BP1, BP0 bits. The Block Protect (BP2, BP1, BP0) bits are non-volatile. They define the size of the area to be software protected against Program and Erase instructions. These bits are written with the Write Status Register (WRSR) instruction. When one or both of the Block Protect (BP2, BP1, BP0) bits is set to 1, the relevant memory area (as defined in Table 3.) becomes protected against Page Program (PP) and Sector Erase (SE) instructions. The Block Protect (BP2, BP1, BP0) bits can be written provided that the Hardware Protected mode has not been set. The Bulk Erase (BE) instruction is executed if, and only if, both Block Protect (BP2, BP1, BP0) bits are 0.

Reserved bit. Status register bit locations 5 and 6 are reserved for future use. Current devices will read 0 for these bit locations. It is recommended to mask out the reserved bit when testing the Status Register. Doing this will ensure compatibility with future devices.

SRP bit. The Status Register Protect (SRP) bit is operated in conjunction with the Write Protect (WP#) signal. The Status Register Write Protect (SRP) bit and Write Protect (WP#) signal allow the device to be put in the Hardware Protected mode (when the Status Register Protect (SRP) bit is set to 1, and Write Protect (WP#) is driven Low). In this mode, the non-volatile bits of the Status Register (SRP, BP2, BP1, BP0) become read-only bits and the Write Status Register (WRSR) instruction is no longer accepted for execution.

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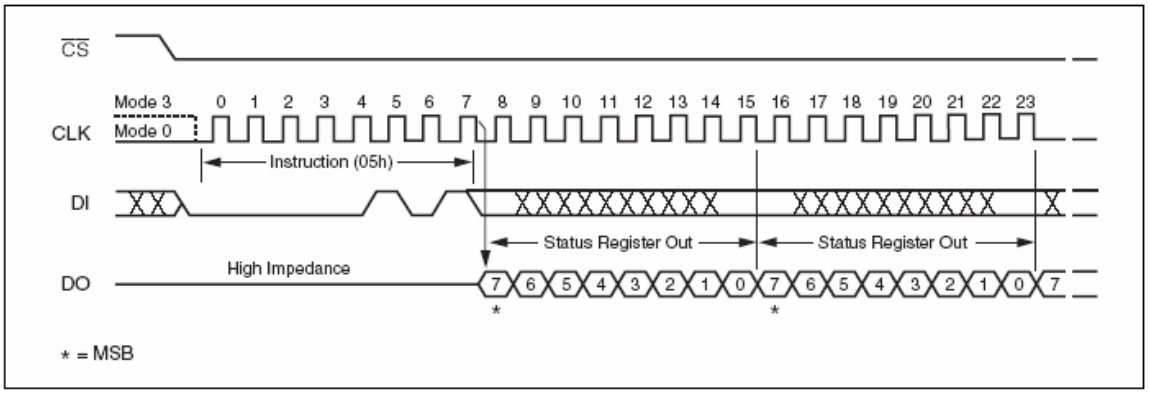


Figure 7. Read Status Register Instruction Sequence Diagram

Write Status Register (WRSR) (01h)

The Write Status Register (WRSR) instruction allows new values to be written to the Status Register. Before it can be accepted, a Write Enable (WREN) instruction must previously have been executed. After the Write Enable (WREN) instruction has been decoded and executed, the device sets the Write Enable Latch (WEL).

The Write Status Register (WRSR) instruction is entered by driving Chip Select (CS#) Low, followed by the instruction code and the data byte on Serial Data Input (DI).

The instruction sequence is shown in Figure 8.. The Write Status Register (WRSR) instruction has no effect on S6, S5, S1 and S0 of the Status Register. S6 and S5 are always read as 0. Chip Select (CS#) must be driven High after the eighth bit of the data byte has been latched in. If not, the Write Status Register (WRSR) instruction is not executed. As soon as Chip Select (CS#) is driven High, the self-timed Write Status Register cycle (whose duration is tW) is initiated. While the Write Status Register cycle is in progress, the Status Register may still be read to check the value of the Write In Progress (WIP) bit. The Write In Progress (WIP) bit is 1 during the self-timed Write Status Register cycle, and is 0 when it is completed. When the cycle is completed, the Write Enable Latch (WEL) is reset.

The Write Status Register (WRSR) instruction allows the user to change the values of the Block Protect (BP2, BP1, BP0) bits, to define the size of the area that is to be treated as read-only, as defined in Table 3.. The Write Status Register (WRSR) instruction also allows the user to set or reset the Status Register Protect (SRP) bit in accordance with the Write Protect (WP#) signal. The Status Register Protect (SRP) bit and Write Protect (WP#) signal allow the device to be put in the Hardware Protected Mode (HPM). The Write Status Register (WRSR) instruction is not executed once the Hardware Protected Mode (HPM) is entered.

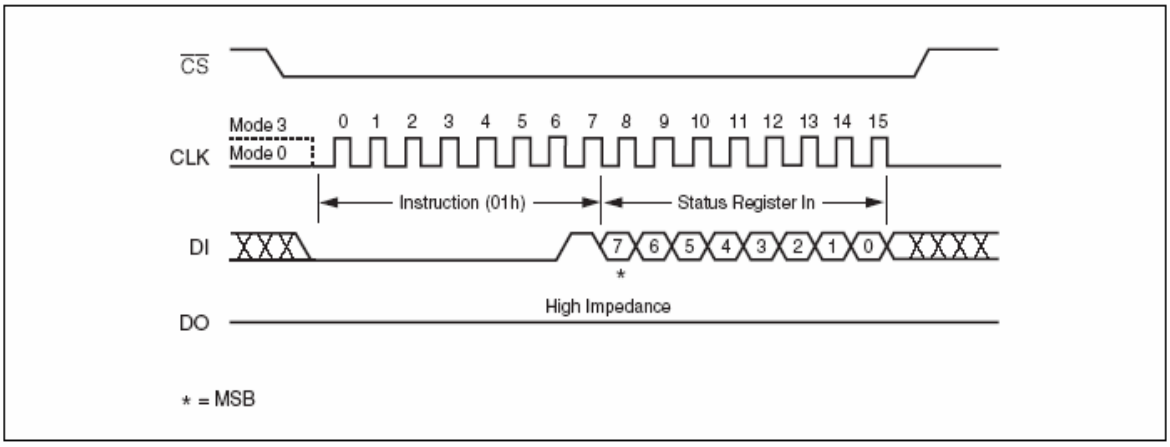


Figure 8. Write Status Register Instruction Sequence Diagram

Read Data Bytes (READ) (03h)

The device is first selected by driving Chip Select (CS#) Low. The instruction code for the Read Data Bytes (READ) instruction is followed by a 3-byte address (A23-A0), each bit being latched-in during the rising edge of Serial Clock (CLK). Then the memory contents, at that address, is shifted out on Serial Data Output (DO), each bit being shifted out, at a maximum frequency f_R, during the falling edge of Serial Clock (CLK).

The instruction sequence is shown in Figure 9.. The first byte addressed can be at any location. The address is automatically incremented to the next higher address after each byte of data is shifted out. The whole memory can, therefore, be read with a single Read Data Bytes (READ) instruction. When the highest address is reached, the address counter rolls over to 000000h, allowing the read sequence to be continued indefinitely.

The Read Data Bytes (READ) instruction is terminated by driving Chip Select (CS#) High. Chip Select (CS#) can be driven High at any time during data output. Any Read Data Bytes (READ) instruction, while an Erase, Program or Write cycle is in progress, is rejected without having any effects on the cycle that is in progress.

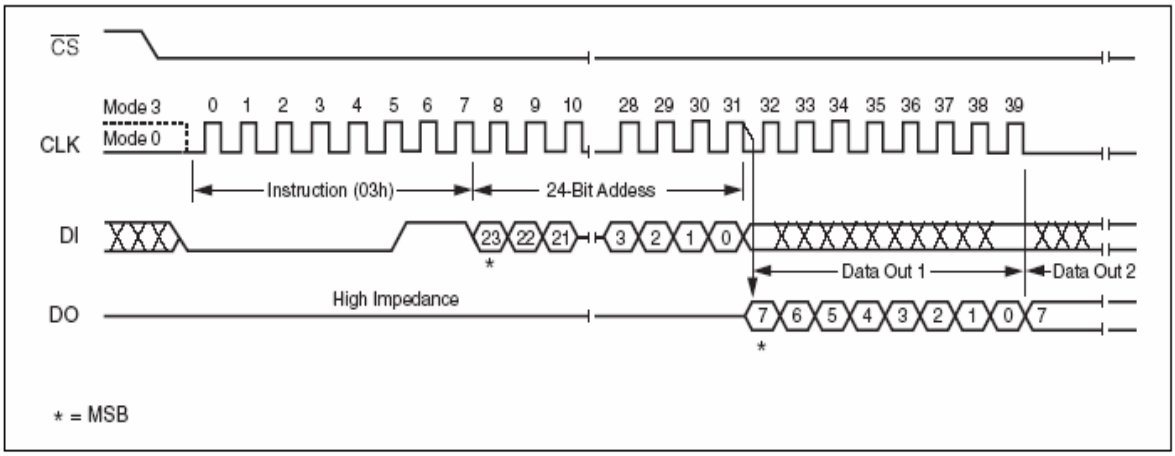


Figure 9. Read Data Instruction Sequence Diagram

Read Data Bytes at Higher Speed (FAST_READ) (0Bh)

The device is first selected by driving Chip Select (CS#) Low. The instruction code for the Read Data Bytes at Higher Speed (FAST_READ) instruction is followed by a 3-byte address (A23-A0) and a dummy byte, each bit being latched-in during the rising edge of Serial Clock (CLK). Then the memory contents, at that address, is shifted out on Serial Data Output (DO), each bit being shifted out, at a maximum frequency F_R, during the falling edge of Serial Clock (CLK).

The instruction sequence is shown in Figure 10.. The first byte addressed can be at any location. The address is automatically incremented to the next higher address after each byte of data is shifted out. The whole memory can, therefore, be read with a single Read Data Bytes at Higher Speed (FAST_READ) instruction. When the highest address is reached, the address counter rolls over to 000000h, allowing the read sequence to be continued indefinitely.

The Read Data Bytes at Higher Speed (FAST_READ) instruction is terminated by driving Chip Select (CS#) High. Chip Select (CS#) can be driven High at any time during data output. Any Read Data Bytes at Higher Speed (FAST_READ) instruction, while an Erase, Program or Write cycle is in progress, is rejected without having any effects on the cycle that is in progress.

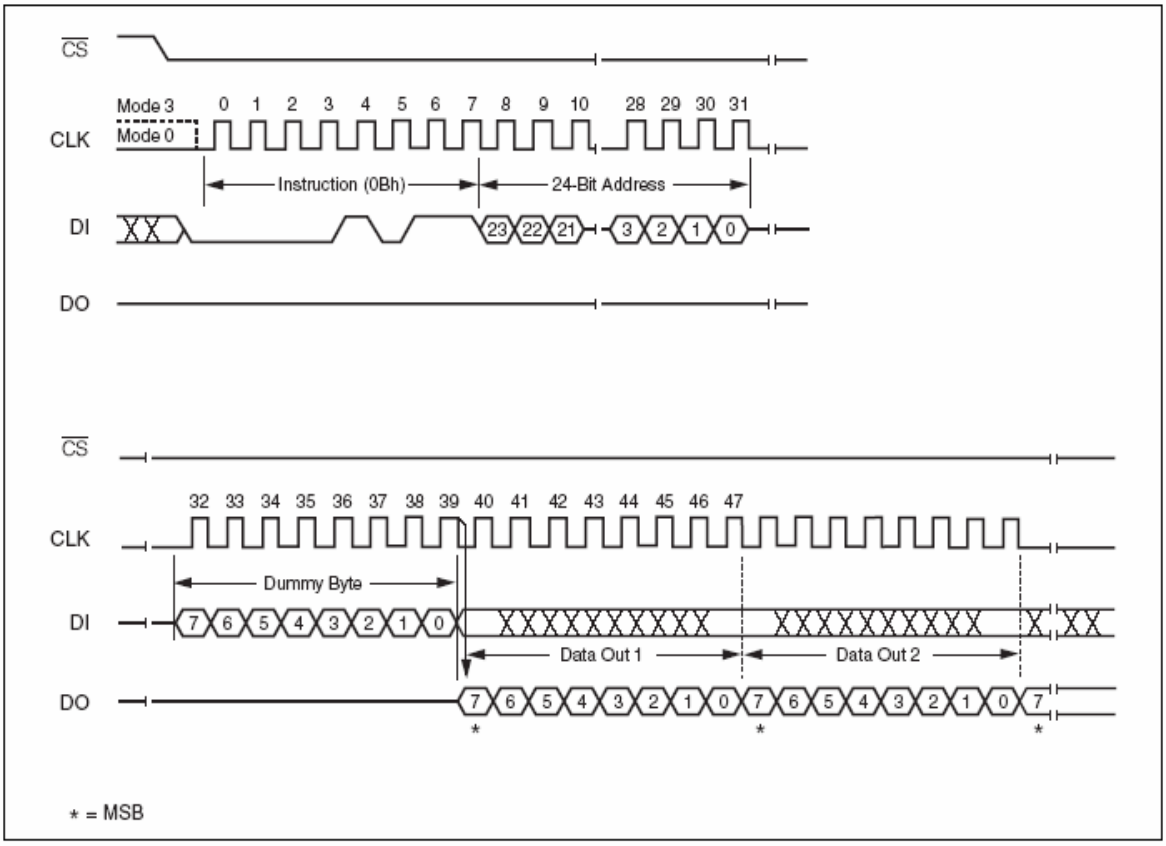


Figure 10. Fast Read Instruction Sequence Diagram

Page Program (PP) (02h)

The Page Program (PP) instruction allows bytes to be programmed in the memory. Before it can be accepted, a Write Enable (WREN) instruction must previously have been executed. After the Write Enable (WREN) instruction has been decoded, the device sets the Write Enable Latch (WEL).

The Page Program (PP) instruction is entered by driving Chip Select (CS#) Low, followed by the instruction code, three address bytes and at least one data byte on Serial Data Input (DI). If the 8 least significant address bits (A7-A0) are not all zero, all transmitted data that goes beyond the end of the current page are programmed from the start address of the same page (from the address whose 8 least significant bits (A7-A0) are all zero). Chip Select (CS#) must be driven Low for the entire duration of the sequence.

The instruction sequence is shown in Figure 11. If more than 256 bytes are sent to the device, previously latched data are discarded and the last 256 data bytes are guaranteed to be programmed correctly within the same page. If less than 256 Data bytes are sent to device, they are correctly programmed at the requested addresses without having any effects on the other bytes of the same page.

Chip Select (CS#) must be driven High after the eighth bit of the last data byte has been latched in, otherwise the Page Program (PP) instruction is not executed.

As soon as Chip Select (CS#) is driven High, the self-timed Page Program cycle (whose duration is t_{PP}) is initiated. While the Page Program cycle is in progress, the Status Register may be read to check the value of the Write In Progress (WIP) bit. The Write In Progress (WIP) bit is 1 during the self-timed Page Program cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset.

A Page Program (PP) instruction applied to a page which is protected by the Block Protect (BP2, BP1, BP0) bits (see Table 3.a and Table 3.b) is not executed.

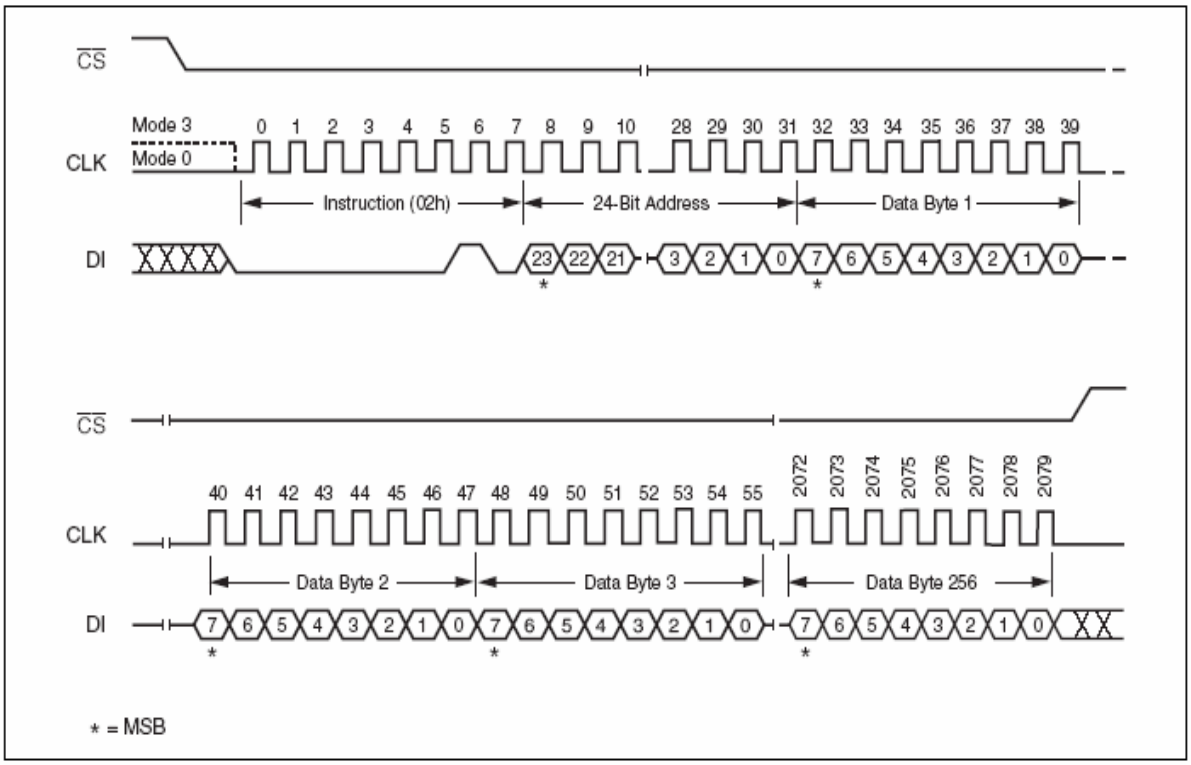


Figure 11. Page Program Instruction Sequence Diagram

Sector Erase (SE) (D8h)

The Sector Erase (SE) instruction sets to 1 (FFh) all bits inside the chosen sector. Before it can be accepted, a Write Enable (WREN) instruction must previously have been executed. After the Write Enable (WREN) instruction has been decoded, the device sets the Write Enable Latch (WEL).

The Sector Erase (SE) instruction is entered by driving Chip Select (CS#) Low, followed by the instruction code, and three address bytes on Serial Data Input (DI). Any address inside the Sector (see Table 2.a and Table 2.b) is a valid address for the Sector Erase (SE) instruction. Chip Select (CS#) must be driven Low for the entire duration of the sequence.

The instruction sequence is shown in Figure 12.. Chip Select (CS#) must be driven High after the eighth bit of the last address byte has been latched in, otherwise the Sector Erase (SE) instruction is not executed. As soon as Chip Select (CS#) is driven High, the self-timed Sector Erase cycle (whose duration is t_{SE}) is initiated. While the Sector Erase cycle is in progress, the Status Register may be read to check the value of the Write In Progress (WIP) bit. The Write In Progress (WIP) bit is 1 during the self-timed Sector Erase cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset.

A Sector Erase (SE) instruction applied to a page which is protected by the Block Protect (BP2, BP1, BP0) bits (see Table 3.a and Table 3.b) is not executed.

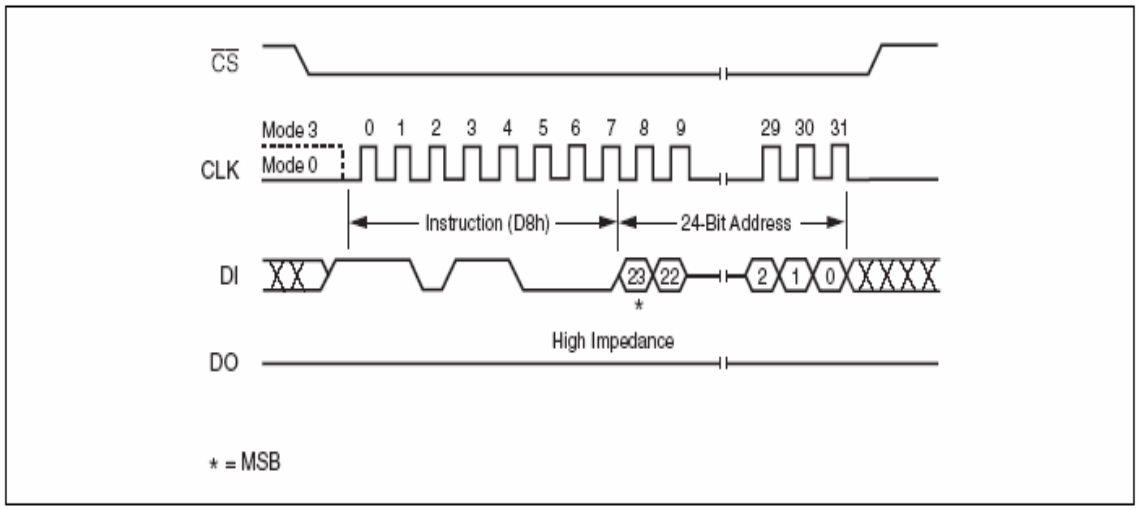


Figure 12. Sector Erase Instruction Sequence Diagram

Bulk Erase (BE) (C7h)

The Bulk Erase (BE) instruction sets all bits to 1 (FFh). Before it can be accepted, a Write Enable (WREN) instruction must previously have been executed. After the Write Enable (WREN) instruction has been decoded, the device sets the Write Enable Latch (WEL).

The Bulk Erase (BE) instruction is entered by driving Chip Select (CS#) Low, followed by the instruction code on Serial Data Input (DI). Chip Select (CS#) must be driven Low for the entire duration of the sequence.

The instruction sequence is shown in Figure 13.. Chip Select (CS#) must be driven High after the eighth bit of the instruction code has been latched in, otherwise the Bulk Erase instruction is not executed. As soon as Chip Select (CS#) is driven High, the self-timed Bulk Erase cycle (whose duration is t_{BE}) is initiated. While the Bulk Erase cycle is in progress, the Status Register may be read to check the value of the Write In Progress (WIP) bit. The Write In Progress (WIP) bit is 1 during the self-timed Bulk Erase cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset.

The Bulk Erase (BE) instruction is executed only if all Block Protect (BP2, BP1, BP0) bits are 0. The Bulk Erase (BE) instruction is ignored if one, or more, sectors are protected.

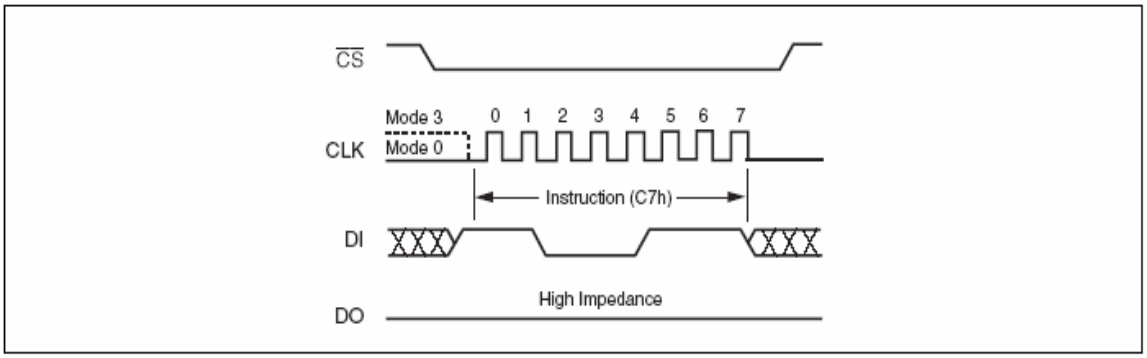


Figure 13. Bulk Erase Instruction Sequence Diagram

Deep Power-down (DP) (B9h)

Executing the Deep Power-down (DP) instruction is the only way to put the device in the lowest consumption mode (the Deep Power-down mode). It can also be used as an extra software protection mechanism, while the device is not in active use, since in this mode, the device ignores all Write, Program and Erase instructions.

Driving Chip Select (CS#) High deselects the device, and puts the device in the Standby mode (if there is no internal cycle currently in progress). But this mode is not the Deep Power-down mode. The Deep Power-down mode can only be entered by executing the Deep Power-down (DP) instruction, to reduce the standby current (from I_{CC1} to I_{CC2}, as specified in Table 8.).

Once the device has entered the Deep Power-down mode, all instructions are ignored except the Release from Deep Power-down and Read Device ID (RDI) instruction. This releases the device from this mode. The Release from Deep Power-down and Read Device ID (RDI) instruction also allows the Device ID of the device to be output on Serial Data Output (DO).

The Deep Power-down mode automatically stops at Power-down, and the device always Powers-up in the Standby mode. The Deep Power-down (DP) instruction is entered by driving Chip Select (CS#) Low, followed by the instruction code on Serial Data Input (DI). Chip Select (CS#) must be driven Low for the entire duration of the sequence.

The instruction sequence is shown in Figure 14..Chip Select (CS#) must be driven High after the eighth bit of the instruction code has been latched in, otherwise the Deep Power-down (DP) instruction is not executed. As soon as Chip Select (CS#) is driven High, it requires a delay of t_{DP} before the supply current is reduced to I_{CC2} and the Deep Power-down mode is entered.

Any Deep Power-down (DP) instruction, while an Erase, Program or Write cycle is in progress, is rejected without having any effects on the cycle that is in progress.

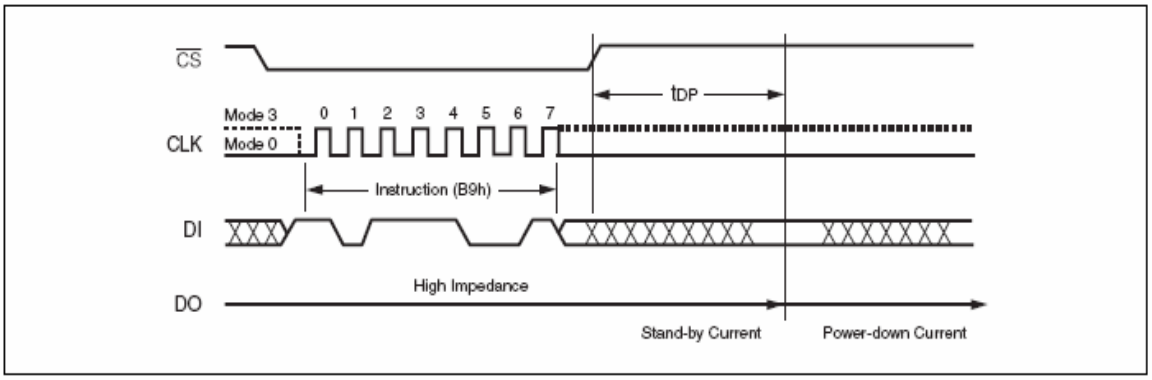


Figure 14. Deep Power-down Instruction Sequence Diagram

Release from Deep Power-down and Read Device ID (RDI)

Once the device has entered the Deep Power-down mode, all instructions are ignored except the Release from Deep Power-down and Read Device ID (RDI) instruction. Executing this instruction takes the device out of the Deep Power-down mode.

Please note that this is not the same as, or even a subset of, the JEDEC 16-bit Electronic Signature that is read by the Read Identifier (RDID) instruction. The old-style Electronic Signature is supported for reasons of backward compatibility, only, and should not be used for new designs. New designs should, instead, make use of the JEDEC 16-bit Electronic Signature, and the Read Identifier (RDID) instruction.

When used only to release the device from the power-down state, the instruction is issued by driving the CS# pin low, shifting the instruction code “ABh” and driving CS# high as shown in Figure 15. After the time duration of t_{RES1} (See AC Characteristics) the device will resume normal operation and other instructions will be accepted. The CS# pin must remain high during the t_{RES1} time duration.

When used only to obtain the Device ID while not in the power-down state, the instruction is initiated by driving the CS# pin low and shifting the instruction code “ABh” followed by 3-dummy bytes. The Device ID bits are then shifted out on the falling edge of CLK with most significant bit (MSB) first as shown in Figure 16. The Device ID value for the EN25P16 are listed in Table 5. The Device ID can be read continuously. The instruction is completed by driving CS# high.

When Chip Select (CS#) is driven High, the device is put in the Stand-by Power mode. If the device was not previously in the Deep Power-down mode, the transition to the Stand-by Power mode is immediate. If the device was previously in the Deep Power-down mode, though, the transition to the Standby Power mode is delayed by t_{RES2}, and Chip Select (CS#) must remain High for at least t_{RES2} (max), as specified in Table 10. Once in the Stand-by Power mode, the device waits to be selected, so that it can receive, decode and execute instructions.

Except while an Erase, Program or Write Status Register cycle is in progress, the Release from Deep Power-down and Read Device ID (RDI) instruction always provides access to the 8bit Device ID of the device, and can be applied even if the Deep Power-down mode has not been entered.

Any Release from Deep Power-down and Read Device ID (RDI) instruction while an Erase, Program or Write Status Register cycle is in progress, is not decoded, and has no effect on the cycle that is in progress.

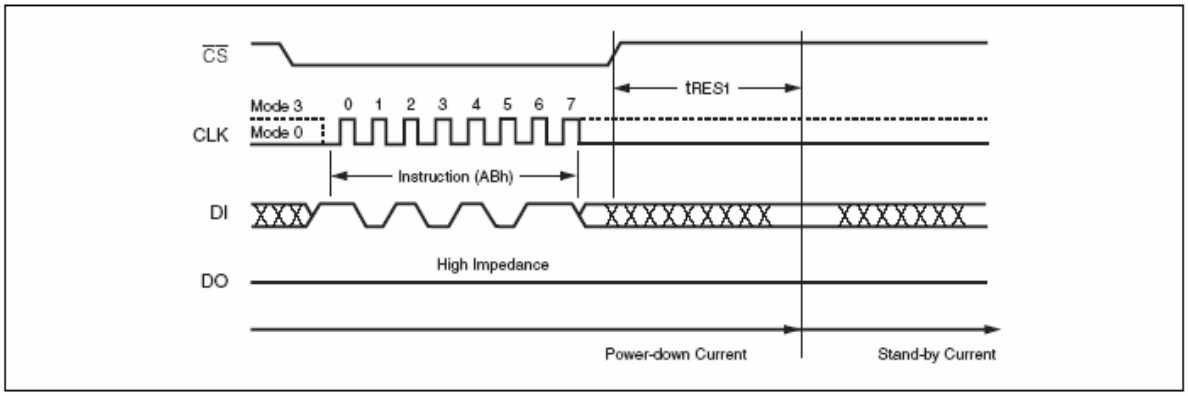


Figure 15. Release Power-down Instruction Sequence

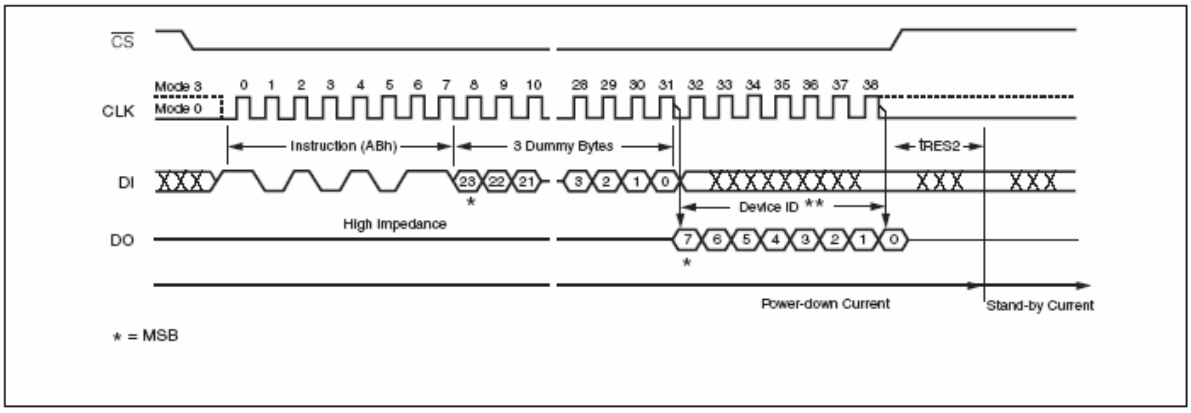


Figure 16. Release Power-down / Device ID Instruction Sequence Diagram

Read Manufacturer / Device ID (90h)

The Read Manufacturer/Device ID instruction is an alternative to the Release from Power-down / Device ID instruction that provides both the JEDEC assigned manufacturer ID and the specific device ID.
The Read Manufacturer/Device ID instruction is very similar to the Release from Power-down / Device ID instruction. The instruction is initiated by driving the CS# pin low and shifting the instruction code “90h” followed by a 24-bit address (A23-A0) of 000000h. After which, the Manufacturer ID for Eon (1Ch) and the Device ID are shifted out on the falling edge of CLK with most significant bit (MSB) first as shown in Figure 17. The Device ID values for the EN25P16 are listed in Table 5. If the 24-bit address is initially set to 000001h the Device ID will be read first

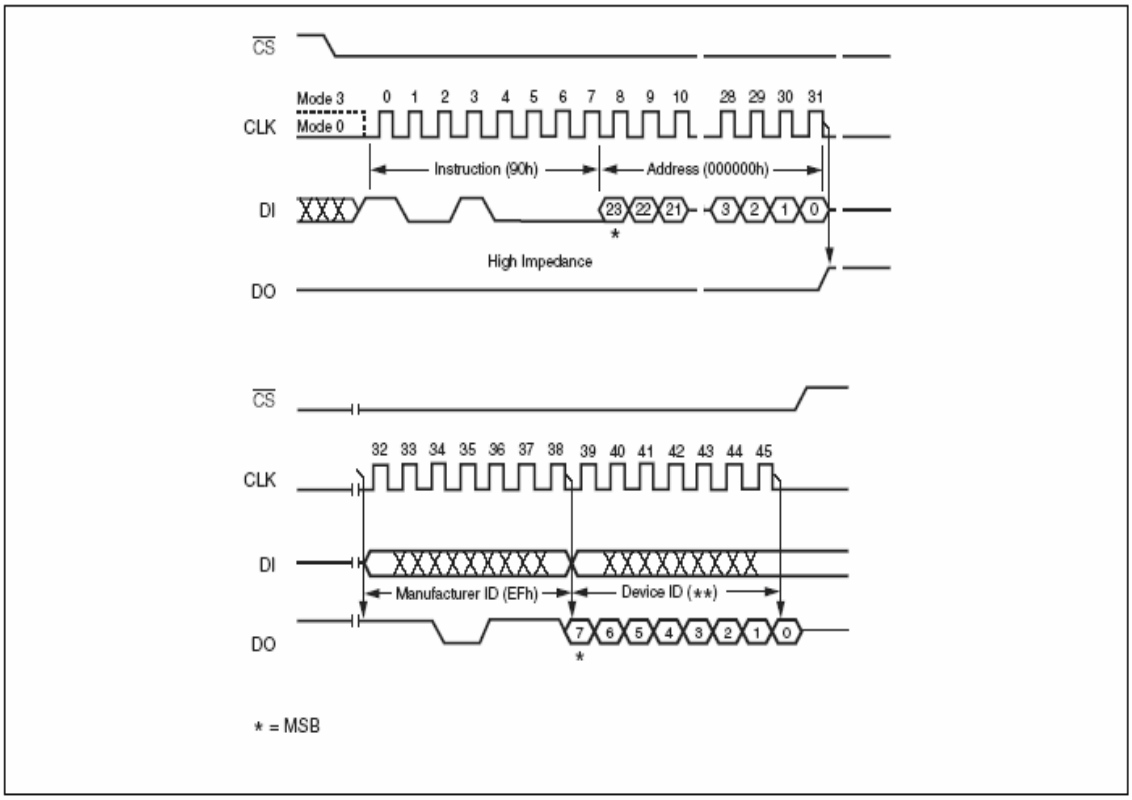


Figure 17. Read Manufacturer / Device ID Diagram

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Read Identification (RDID)(9Fh)

The Read Identification (RDID) instruction allows the 8-bit manufacturer identification to be read, followed by two bytes of device identification. The device identification indicates the memory type in the first byte , and the memory capacity of the device in the second byte .

Any Read Identification (RDID) instruction while an Erase or Program cycle is in progress, is not decoded, and has no effect on the cycle that is in progress. The Read Identification (RDID) instruction should not be issued while the device is in Deep Power down mode.

The device is first selected by driving Chip Select Low. Then, the 8-bit instruction code for the instruction is shifted in. This is followed by the 24-bit device identification, stored in the memory, being shifted out on Serial Data Output , each bit being shifted out during the falling edge of Serial Clock . The instruction sequence is shown in Figure 18. The Read Identification (RDID) instruction is terminated by driving Chip Select High at any time during data output.

When Chip Select is driven High, the device is put in the Standby Power mode. Once in the Standby Power mode, the device waits to be selected, so that it can receive, decode and execute instructions.

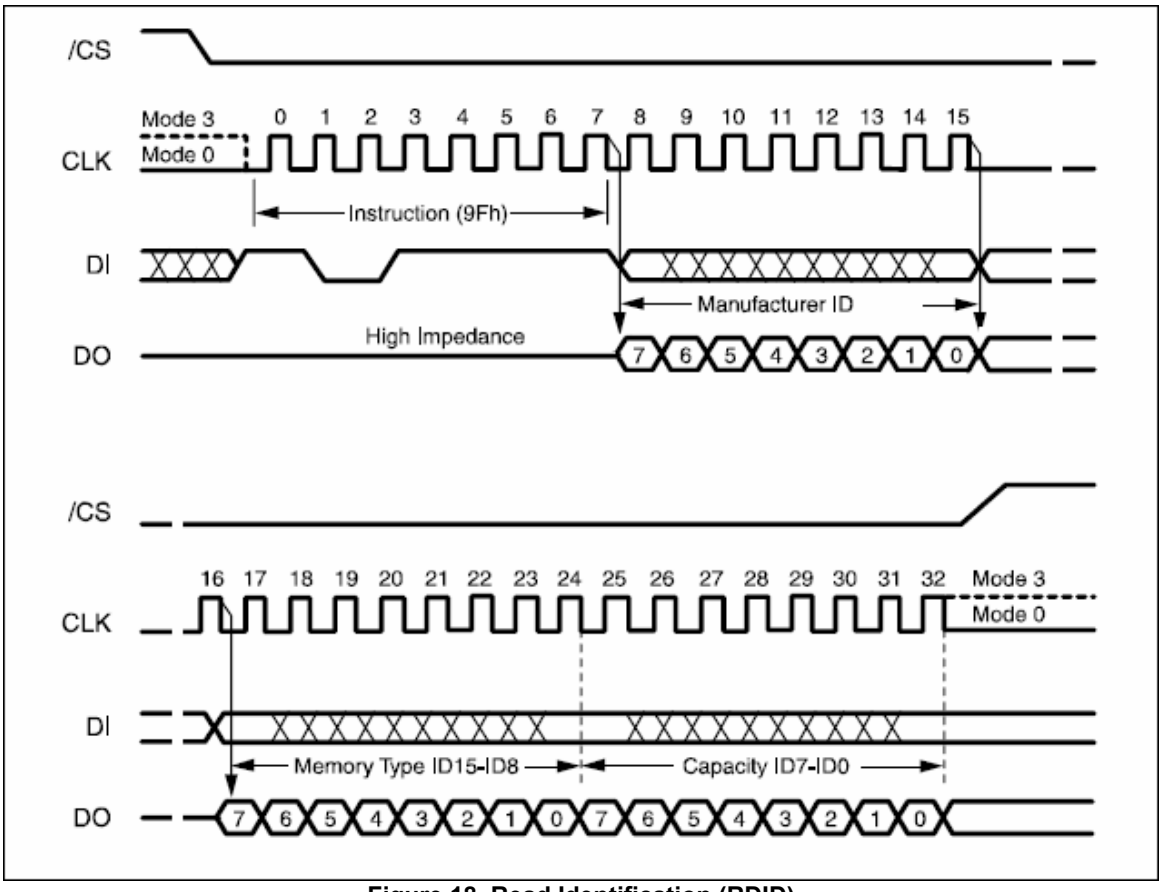


Figure 18. Read Identification (RDID)

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Power-up Timing

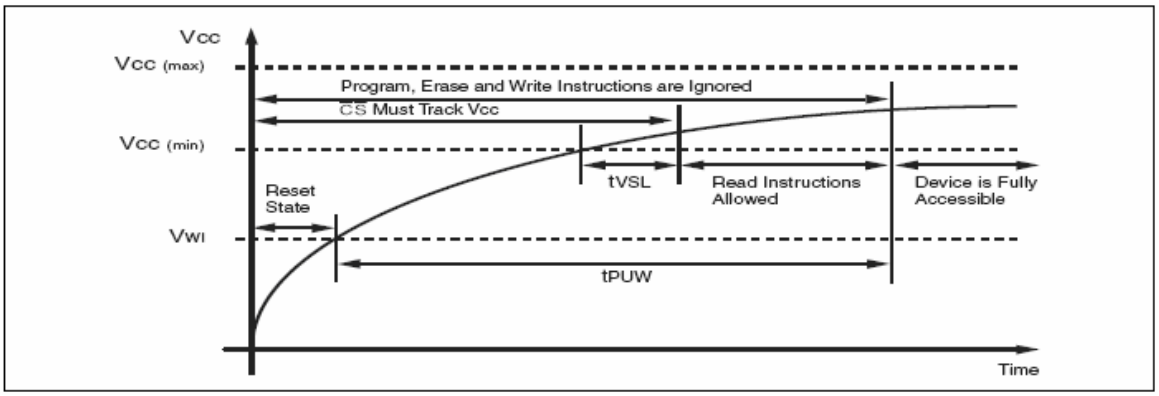


Figure 19. Power-up Timing

Table 7. Power-Up Timing and Write Inhibit Threshold

Symbol	Parameter	Min.	Max.	Unit
t_{VSL}(1)	VCC(min) to CS# low	10		µs
t_{PUW}(1)	Time delay to Write instruction	1	10	ms
V_{WI}(1)	Write Inhibit Voltage	1	2	V

Note:
1.The parameters are characterized only.

INITIAL DELIVERY STATE

The device is delivered with the memory array erased: all bits are set to 1 (each byte contains FFh). The Status Register contains 00h (all Status Register bits are 0).

Table 8. DC Characteristics

(T_a = 0°C to 70°C or - 40°C to 85°C; V_{CC} = 2.7-3.6V)

Symbol	Parameter	Test Conditions	Min.	Max.	Unit
I_{LI}	Input Leakage Current			± 2	µA
I_{LO}	Output Leakage Current			± 2	µA
I_{CC1}	Standby Current	CS# = V_{CC}, V_{IN} = V_{SS} or V_{CC}		10	µA
I_{CC2}	Deep Power-down Current	CS# = V_{CC}, V_{IN} = V_{SS} or V_{CC}		10	µA
I_{CC3}	Operating Current (READ)	CLK = 0.1 V_{CC} / 0.9 V_{CC} at 75MHz, Q = open		20	mA
		CLK = 0.1 V_{CC} / 0.9 V_{CC} at 50MHz, Q = open		15	mA
		CLK = 0.1 V_{CC} / 0.9 V_{CC} at 33MHz, Q = open		12	mA
I_{CC4}	Operating Current (PP)	CS# = V_{CC}		15	mA
I_{CC5}	Operating Current (WRSR)	CS# = V_{CC}		15	mA
I_{CC6}	Operating Current (SE)	CS# = V_{CC}		15	mA
I_{CC7}	Operating Current (BE)	CS# = V_{CC}		15	mA
V_{IL}	Input Low Voltage		– 0.5	0.2 V_{CC}	V
V_{IH}	Input High Voltage		0.7V_{CC}	V_{CC}+0.4	V
V_{OL}	Output Low Voltage	I_{OL} = 1.6 mA		0.4	V
V_{OH}	Output High Voltage	I_{OH} = –100 µA	V_{CC}-0.2		V

Table 9. AC Measurement Conditions

Symbol	Parameter	Min.	Max.	Unit
C_L	Load Capacitance	30		pF
	Input Rise and Fall Times		5	ns
	Input Pulse Voltages	0.2V_{CC} to 0.8V_{CC}		V
	Input Timing Reference Voltages	0.3V_{CC} to 0.7V_{CC}		V
	Output Timing Reference Voltages	V_{CC} / 2		V

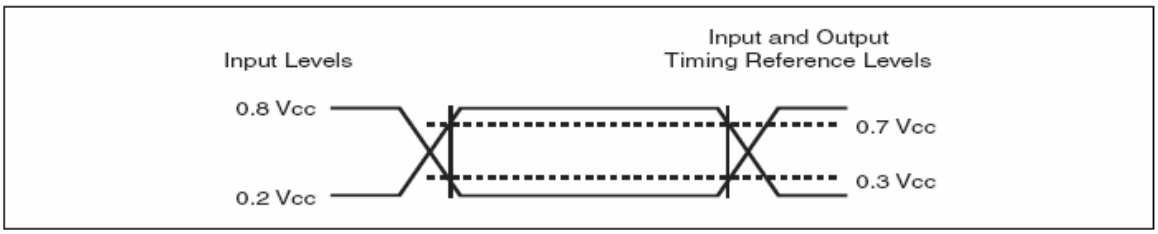


Figure 20. AC Measurement I/O Waveform

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Table 10. 75MHz AC Characteristics

(T_a = 0°C to 70°C or – 40°C to 85°C; V_{CC} = 2.7-3.6V)

Symbol	Alt	Parameter	Min	Typ	Max	Unit
F_R	f_C	Serial Clock Frequency for: FAST_READ, PP, SE, BE, DP, RES, WREN, WRDI, RDSR, WRSR	D.C.		75	MHz
f_R		Serial Clock Frequency READ instruction	D.C.		50	MHz
t_{CLH} [1]		Serial Clock High Time	6			ns
t_{CLL} [1]		Serial Clock Low Time	6			ns
t_{CLCH} [2]		Serial Clock Rise Time (Slew Rate)	0.1			V / ns
t_{CHCL} [2]		Serial Clock Fall Time (Slew Rate)	0.1			V / ns
t_{SLCH}	t_{CSS}	CS# Active Setup Time	5			ns
t_{CHSH}		CS# Active Hold Time	5			ns
t_{SHCH}		CS# Not Active Setup Time	5			ns
t_{CHSL}		CS# Not Active Hold Time	5			ns
t_{SHSL}	t_{CSH}	CS# High Time	100			ns
t_{SHQZ} [2]	t_{DIS}	Output Disable Time			6	ns
t_{CLQX}	t_{HO}	Output Hold Time	0			ns
t_{DVCH}	t_{DSU}	Data In Setup Time	2			ns
t_{CHDX}	t_{DH}	Data In Hold Time	5			ns
t_{HLCH}		HOLD# Low Setup Time (relative to SCK)	5			ns
t_{HHCH}		HOLD# High Setup Time (relative to SCK)	5			ns
t_{CHHH}		HOLD# Low Hold Time (relative to SCK)	5			ns
t_{CHHL}		HOLD# High Hold Time (relative to SCK)	5			ns
t_{HLQZ} [2]	t_{HZ}	HOLD# Low to High-Z Output			6	ns
t_{HHQZ} [2]	t_{LZ}	HOLD# High to Low-Z Output			6	ns
t_{CLQV}	t_V	Output Valid from SCK			6	ns
t_{WHSL} [3]		Write Protect Setup Time before CS# Low	20			ns
t_{SHWL} [3]		Write Protect Hold Time after CS# High	100			ns
t_{DP} [2]		CS# High to Deep Power-down Mode			3	µs
t_{RES1} [2]		CS# High to Standby Mode without Electronic Signature read			3	µs
t_{RES2} [2]		CS# High to Standby Mode with Electronic Signature read			1.8	µs
t_W		Write Status Register Cycle Time		10	15	ms
t_{PP}		Page Programming Time		1.5	5	ms
t_{SE}		Sector Erase Time sectors		0.8	2	s
t_{BE}		Bulk Erase Time		18	35	s

Note: 1. $T_{SCKH} + T_{SCKL}$ must be greater than or equal to 1/ F_{CLK}
2. Value guaranteed by characterization, not 100% tested in production.
3. Only applicable as a constraint for a Write status Register instruction when Status Register Protect Bit is set at 1.

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Table 11. 50MHz AC Characteristics

(T_a = 0°C to 70°C or – 40°C to 85°C; V_{CC} = 2.7-3.6V)

Symbol	Alt	Parameter	Min	Typ	Max	Unit
F_R	f_C	Serial Clock Frequency for: FAST_READ, PP, SE, BE, DP, RES, WREN, WRDI, RDSR, WRSR	D.C.		50	MHz
f_R		Serial Clock Frequency READ instruction	D.C.		33	MHz
t_{CLH} [1]		Serial Clock High Time	9			ns
t_{CLL} [1]		Serial Clock Low Time	9			ns
t_{CLCH} [2]		Serial Clock Rise Time (Slew Rate)	0.1			V / ns
t_{CHCL} [2]		Serial Clock Fall Time (Slew Rate)	0.1			V / ns
t_{SLCH}	t_{CSS}	CS# Active Setup Time	5			ns
t_{CHSH}		CS# Active Hold Time	5			ns
t_{SHCH}		CS# Not Active Setup Time	5			ns
t_{CHSL}		CS# Not Active Hold Time	5			ns
t_{SHSL}	t_{CSH}	CS# High Time	100			ns
t_{SHQZ} [2]	t_{DIS}	Output Disable Time			9	ns
t_{CLQX}	t_{HO}	Output Hold Time	0			ns
t_{DVCH}	t_{DSU}	Data In Setup Time	2			ns
t_{CHDX}	t_{DH}	Data In Hold Time	5			ns
t_{HLCH}		HOLD# Low Setup Time (relative to SCK)	5			ns
t_{HHCH}		HOLD# High Setup Time (relative to SCK)	5			ns
t_{CHHH}		HOLD# Low Hold Time (relative to SCK)	5			ns
t_{CHHL}		HOLD# High Hold Time (relative to SCK)	5			ns
t_{HLQZ} [2]	t_{HZ}	HOLD# Low to High-Z Output			9	ns
t_{HHQZ} [2]	t_{LZ}	HOLD# High to Low-Z Output			9	ns
t_{CLQV}	t_V	Output Valid from SCK			9	ns
t_{WHSL} [3]		Write Protect Setup Time before CS# Low	20			ns
t_{SHWL} [3]		Write Protect Hold Time after CS# High	100			ns
t_{DP} [2]		CS# High to Deep Power-down Mode			3	µs
t_{RES1} [2]		CS# High to Standby Mode without Electronic Signature read			3	µs
t_{RES2} [2]		CS# High to Standby Mode with Electronic Signature read			1.8	µs
t_W		Write Status Register Cycle Time		10	15	ms
t_{PP}		Page Programming Time		1.5	5	ms
t_{SE}		Sector Erase Time sectors		0.8	2	s
t_{BE}		Bulk Erase Time		18	35	s

Note: 1. $T_{SCKH} + T_{SCKL}$ must be greater than or equal to 1/ F_{CLK}
2. Value guaranteed by characterization, not 100% tested in production.
3. Only applicable as a constraint for a Write status Register instruction when Status Register Protect Bit is set at 1.

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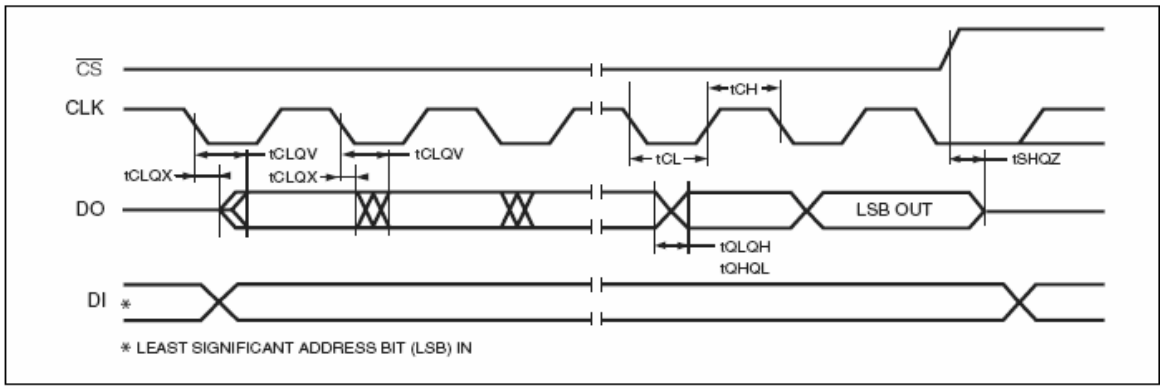


Figure 21. Serial Output Timing

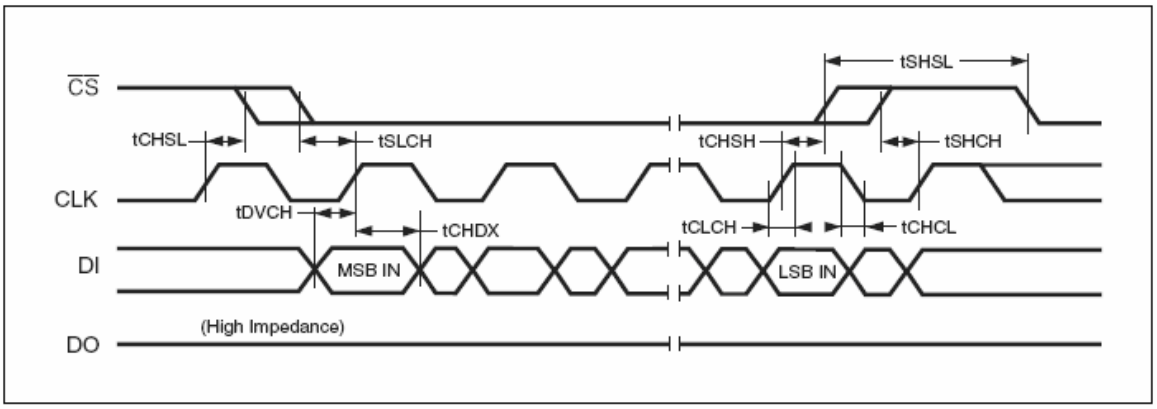


Figure 22. Input Timing

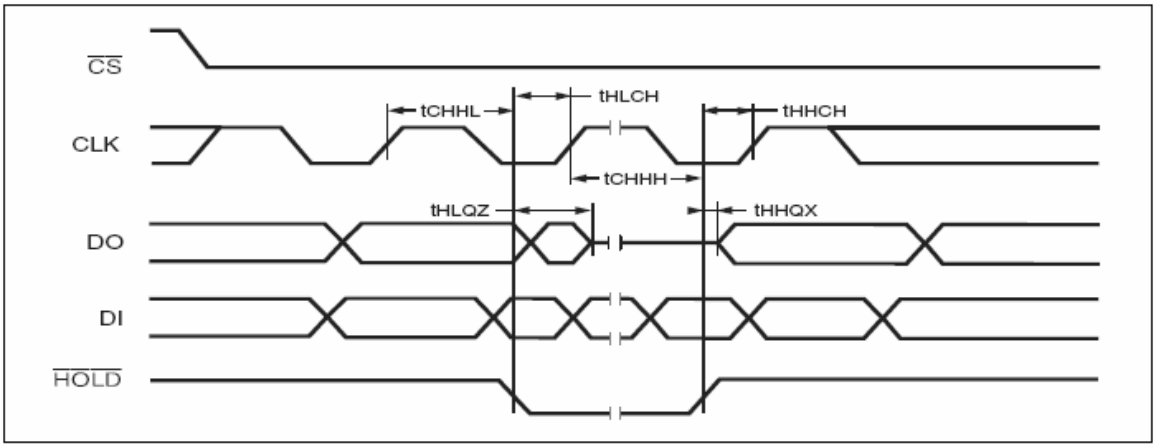


Figure 23. Hold Timing

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ABSOLUTE MAXIMUM RATINGS

Stresses above the values so mentioned above may cause permanent damage to the device. These values are for a stress rating only and do not imply that the device should be operated at conditions up to or above these values. Exposure of the device to the maximum rating values for extended periods of time may adversely affect the device reliability.

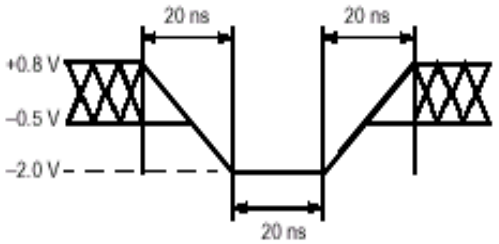
Parameter	Value	Unit
Storage Temperature	-65 to +125	°C
Plastic Packages	-65 to +125	°C
Output Short Circuit Current[1]	200	mA
Input and Output Voltage (with respect to ground) [2]	-0.5 to +4.0	V
Vcc	-0.5 to +4.0	V

Notes:
1. No more than one output shorted at a time. Duration of the short circuit should not be greater than one second.
2. Minimum DC voltage on input or I/O pins is –0.5 V. During voltage transitions, inputs may undershoot V_{ss} to –1.0V for periods of up to 50ns and to –2.0 V for periods of up to 20ns. See figure below. Maximum DC voltage on output and I/O pins is V_{cc} + 0.5 V. During voltage transitions, outputs may overshoot to V_{cc} + 1.5 V for periods up to 20ns. See figure below.

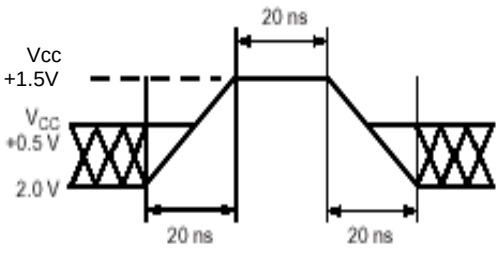
RECOMMENDED OPERATING RANGES [1]

Parameter	Value	Unit
Ambient Operating Temperature Commercial Devices Industrial Devices	0 to 70 -40 to 85	°C
Operating Supply Voltage Vcc	Regulated: 3.0 to 3.6	V
	Full: 2.7 to 3.6	

Notes:
16 Recommended Operating Ranges define those limits between which the functionality of the device is guaranteed.



Maximum Negative Overshoot Waveform



Maximum Positive Overshoot Waveform

Table 12. DATA RETENTION and ENDURANCE

Parameter Description	Test Conditions	Min	Unit
Minimum Pattern Data Retention Time	150°C	10	Years
	125°C	20	Years
Erase/Program Endurance	-40 to 85 °C	100k	cycles

Table 13. LATCH UP CHARACTERISTICS

Parameter Description	Min	Max
Input voltage with respect to V_{ss} on all pins except I/O pins (including A9, Reset and OE#)	-1.0 V	12.0 V
Input voltage with respect to V_{ss} on all I/O Pins	-1.0 V	Vcc + 1.0 V
Vcc Current	-100 mA	100 mA

Note : These are latch up characteristics and the device should never be put under these conditions. Refer to Absolute Maximum ratings for the actual operating limits.

Table 14. CAPACITANCE

(V_{CC} = 2.7-3.6V)

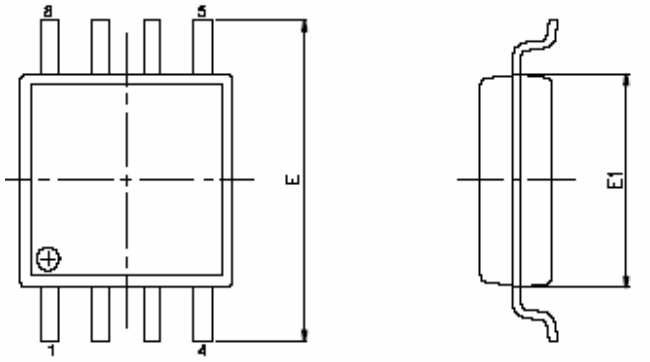
Parameter Symbol	Parameter Description	Test Setup	Typ	Max	Unit
C_{IN}	Input Capacitance	V_{IN} = 0		6	pF
C_{OUT}	Output Capacitance	V_{OUT} = 0		8	pF

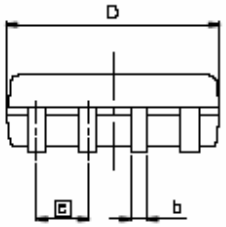
Note : Sampled only, not 100% tested, at T_A = 25°C and a frequency of 20MHz.

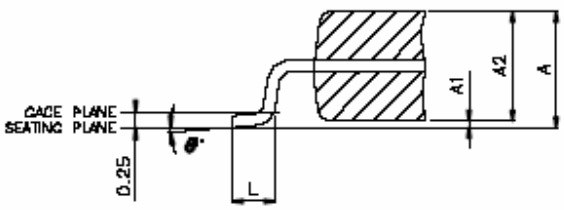
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PACKAGE MECHANICAL

Figure 24. 8 LEAD SOP 200 mil (official name = 209 mil)





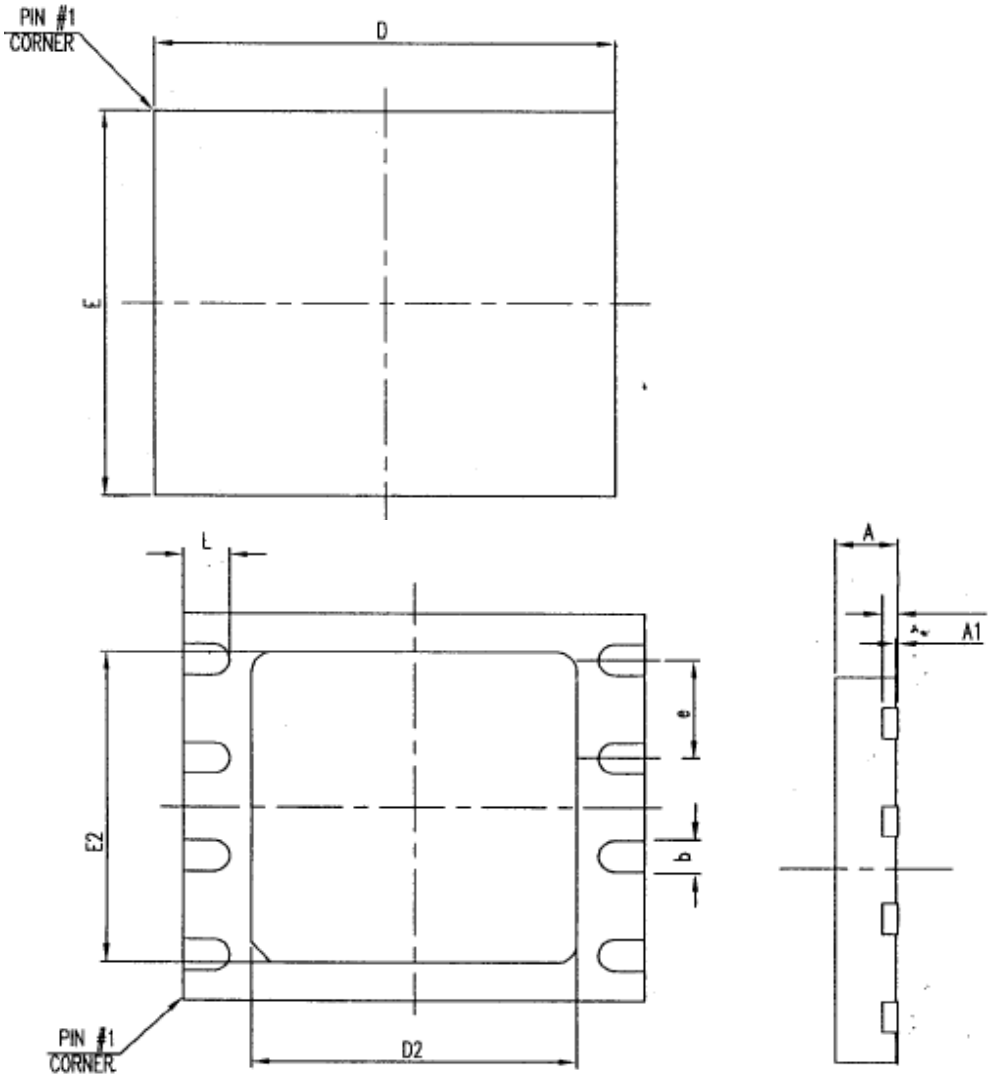


SYMBOLS	MIN.	NOM.	MAX.
A	1.750	1.975	2.200
A1	0.050	0.150	0.250
A2	1.700	1.825	1.950
b	0.350	0.425	0.500
c	0.190	0.220	0.250
D	5.150	5.275	5.400
E	7.700	7.900	8.100
E1	5.150	5.275	5.400
e		1.27 BSC	
L	0.500	0.650	0.800
θ°	0°	4°	8°

UNIT : MM

NOTES :
1. JEDEC OUTLINE : N/A.
2. COPLANARITY : 0.1MM.
3. MAXIMUM ALLOWABLE MOLD FLASH IS 0.15MM AT THE PACKAGE ENDS AND 0.25MM BETWEEN LEADS.

Figure 25. VDFN8(5x6mm)

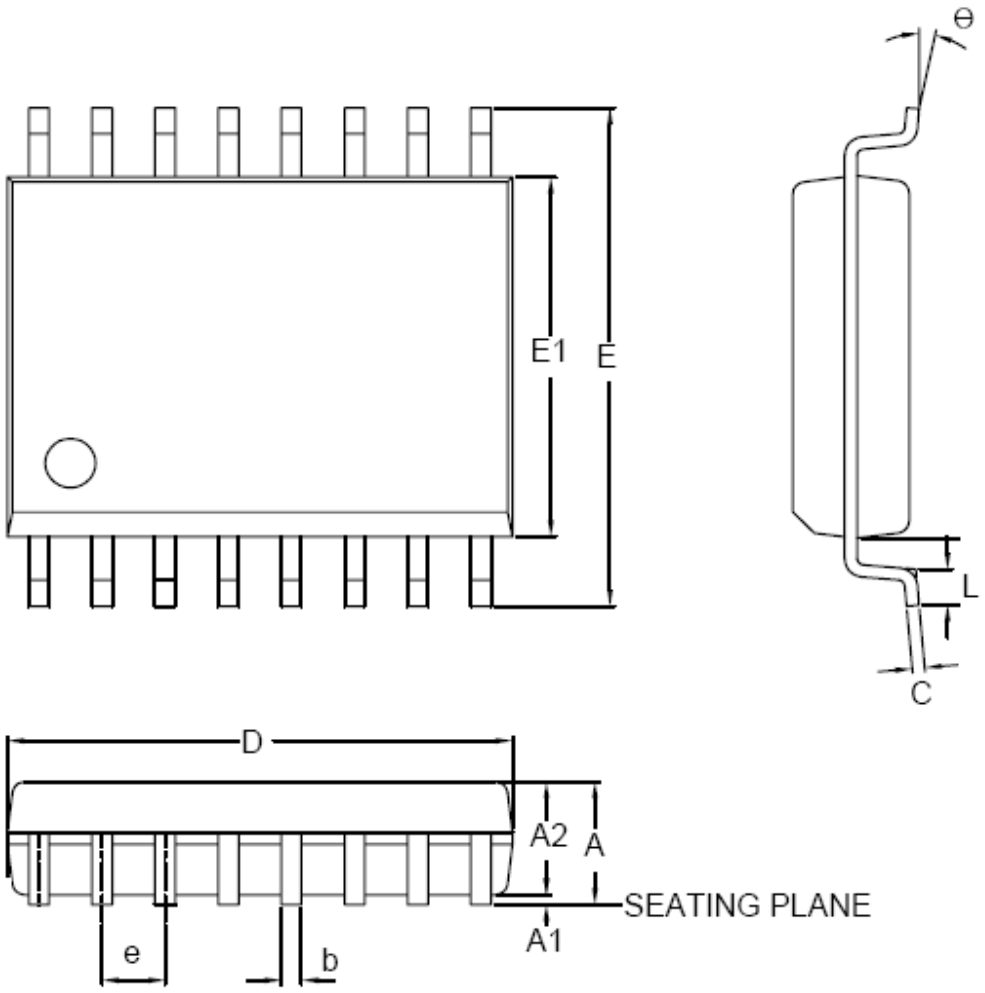


SYMBOL	DIMENSION IN MM		
	MIN.	NOR	MAX
A	0.76	0.80	0.84
A1	0.00	0.02	0.04
A2	- - -	0.20	- - -
D	5.90	6.00	6.10
E	4.90	5.00	5.10
D2	4.18	4.23	4.28
E2	3.95	4.00	4.05
e	- - -	1.27	- - -
b	0.35	0.40	0.45
L	0.55	0.60	0.65

Note : 1. Coplanarity: 0.1 mm

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Figure 26. 16 LEAD SOP 300 mil



SYMBOL	DIMENSION IN MM		
	MIN.	NOR	MAX
A	- - -	- - -	2.65
A1	0.10	0.20	0.30
A2	2.25	- - -	2.40
C	0.20	0.25	0.30
D	10.10	10.30	10.50
E	10.00	- - -	10.65
E1	7.40	7.50	7.60
e	- - -	1.27	- - -
b	0.31	- - -	0.51
L	0.4	- - -	1.27
θ	0^0	5^0	8^0

Note : 1. Coplanarity: 0.1 mm

ORDERING INFORMATION

EN25P16 - 50 H C P

PACKAGING CONTENT
(Blank) = Conventional
P = Lead-free package can represent and warrant meeting the requirements of the current RoHS Directive 2002/95/EC.

TEMPERATURE RANGE
C = Commercial (0°C to +70°C)
I = Industrial (-40°C to +85°C)

PACKAGE
F = 16-pin 300mil SOP
H = 8-pin 200mil SOP
V = 8-pin VDFN

SPEED
75 = 75 Mhz
50 = 50 Mhz

BASE PART NUMBER
EN = Eon Silicon Solution Inc.
25P = 3V Serial Uniform-Sector FLASH
16 = 16 Megabit (2048K x 8)

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Revisions List

Revision No	Description	Date
A	Initial release	2006/05/25
B	1. Add 16 pin SOP 300mil body width for package options in page 1 2. Add 16 pin SOP 300mil diagram in Figure 1 3. Add INSTRUCTIONS description in page 9 4. Add figure 26 of SOP 300mil package 5. Add 16 pin SOP package option 'F' to ordering info	2006/08/08
C	1. Change clock rate from 50MHz to 75MHz, Page program time 1.4 ms typical to 1.5 ms typical Sector erase time 300 ms typical to 800 ms Chip erase time 10 seconds to 18 seconds typical in page 1 2. Change Table 8 DC Characteristics in page 22 (1) Add I_{CC3} for 75MHz 3. Change Table 10 to 75MHz AC Characteristics in page 23 (1) Change F_R from 50 to 75MHz (2) Change f_R from 33 to 50MHz (3) Change t_{CLH} from 9ns to 6ns (4) Change t_{CLL} from 9ns to 6ns (5) Change t_{SHQZ} from 9ns to 6ns (6) Change t_{HLQZ} from 9ns to 6ns (7) Change t_{HHQZ} from 9ns to 6ns (8) Change t_{CLQV} from 9ns to 6ns (9) Change Page program time 1.4ms typical to 1.5ms (10) Change Sector erase time 0.3 / 0.6 seconds to 0.8 / 2 seconds for typical and maximum (11)Change Chip erase time 10 / 20 seconds to 18 / 35 seconds for typical and maximum 4. Add Table 11: 50MHz AC Characteristics in page 24 (1) Change Page program time 1.4ms typical to 1.5ms (2) Change Sector erase time 0.3 / 0.6 seconds to 0.8 / 2 seconds for typical and maximum (3) Change Chip erase time 10 / 20 seconds to 18 / 35 seconds for typical and maximum 5. Add 75MHz option in Ordering Information in page 31 6. Change Table 8. DC Characteristics V_{IL} Max 0.3 V_{CC} to 0.2 V_{CC} in page 22	2006/12/25