











SNVS316G - SEPTEMBER 2004-REVISED DECEMBER 2014

LM2736

# LM2736 Thin SOT 750 mA Load Step-Down DC-DC Regulator

#### **Features**

- Thin SOT-6 Package
- 3.0 V to 18 V Input Voltage Range
- 1.25 V to 16 V Output Voltage Range
- 750 mA Output Current
- 550 kHz (LM2736Y) and 1.6 MHz (LM2736X) Switching Frequencies
- 350 mΩ NMOS Switch
- 30 nA Shutdown Current
- 1.25 V, 2% Internal Voltage Reference
- Internal Soft-Start
- Current-Mode, PWM Operation
- WEBENCH® Online Design Tool
- Thermal Shutdown

### **Applications**

- Local Point of Load Regulation
- Core Power in HDDs
- Set-Top Boxes
- **Battery Powered Devices**
- **USB Powered Devices**
- **DSL Modems**
- **Notebook Computers**

### 3 Description

The LM2736 regulator is a monolithic, high frequency, PWM step-down DC/DC converter in a 6-pin Thin SOT package. It provides all the active functions to provide local DC/DC conversion with fast transient response and accurate regulation in the smallest possible PCB area.

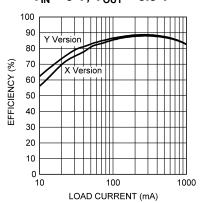
With a minimum of external components and online design support through WEBENCH®, the LM2736 is easy to use. The ability to drive 750 mA loads with an internal 350 mΩ NMOS switch using state-of-the-art 0.5 µm BiCMOS technology results in the best power density available. The world class control circuitry allows for on-times as low as 13 ns, thus supporting exceptionally high frequency conversion over the entire 3 V to 18 V input operating range down to the minimum output voltage of 1.25 V. Switching frequency is internally set to 550 kHz (LM2736Y) or 1.6 MHz (LM2736X), allowing the use of extremely small surface mount inductors and chip capacitors. Even though the operating frequencies are very high, efficiencies up to 90% are easy to achieve. External shutdown is included, featuring an ultra-low stand-by current of 30 nA. The LM2736 utilizes current-mode control and internal compensation to provide highperformance regulation over a wide range of operating conditions. Additional features include internal soft-start circuitry to reduce inrush current, pulse-by-pulse current limit, thermal shutdown, and output over-voltage protection.

#### Device Information<sup>(1)</sup>

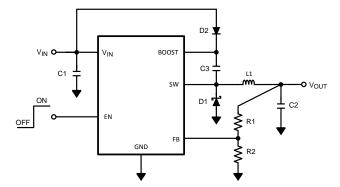
PART NUMBER	PACKAGE	BODY SIZE (NOM)
LM2736	SOT (6)	2.90 mm x 1.60 mm

(1) For all available packages, see the orderable addendum at the end of the datasheet.

Efficiency vs. Load Current "X"  $V_{IN} = 5 \text{ V}, V_{OUT} = 3.3 \text{ V}$ 



#### **Typical Application Circuit**





# **Table of Contents**

1	Features 1		7.4 Device Functional Modes	
2	Applications 1	8	Application and Implementation	11
3	Description 1		8.1 Application Information	1
4	Revision History2		8.2 Typical Applications	13
5	Pin Configuration and Functions3	9	Power Supply Recommendations	20
6	Specifications4	10	Layout	2
•	6.1 Absolute Maximum Ratings		10.1 Layout Guidelines	2
	6.2 ESD Ratings 4		10.2 Layout Example	2
	6.3 Recommended Operating Conditions	11	Device and Documentation Support	29
	6.4 Thermal Information		11.1 Device Support	29
	6.5 Electrical Characteristics 5		11.2 Documentation Support	2
	6.6 Typical Characteristics		11.3 Trademarks	29
7	Detailed Description 8		11.4 Electrostatic Discharge Caution	2
•	7.1 Overview 8		11.5 Glossary	29
	7.2 Functional Block Diagram	12	Mechanical, Packaging, and Orderable	
	7.3 Feature Description9		Information	30

# 4 Revision History

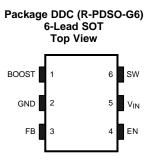
### Changes from Revision F (April 2013) to Revision G

**Page** 

Add Handling Rating table, Feature Description section, Device Functional Modes, Application and Implementation section, Power Supply Recommendations section, Layout section, Device and Documentation Support section, and 



# 5 Pin Configuration and Functions



# **Pin Functions**

PIN		1/0	DESCRIPTION		
NAME	NO.	1/0	DESCRIPTION		
BOOST 1 Boost voltage that drives the internal NMOS control switch. A bootstrap capacitor i connected between the BOOST and SW pins.		Boost voltage that drives the internal NMOS control switch. A bootstrap capacitor is connected between the BOOST and SW pins.			
GND 2 GND Signal and Power ground pin. Place the bottom resistor of the feedback network as possible to this pin for accurate regulation.		Signal and Power ground pin. Place the bottom resistor of the feedback network as close as possible to this pin for accurate regulation.			
FB	3	1	Feedback pin. Connect FB to the external resistor divider to set output voltage.		
EN	4	I	Enable control input. Logic high enables operation. Do not allow this pin to float or be greathan $V_{\text{IN}}$ + 0.3 V.		
V <sub>IN</sub>	5	I	Input supply voltage. Connect a bypass capacitor to this pin.		
SW 6 O		0	Output switch. Connects to the inductor, catch diode, and bootstrap capacitor.		

Copyright © 2004–2014, Texas Instruments Incorporated



# 6 Specifications

### 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT
V <sub>IN</sub>		-0.5	22	V
SW Voltage		-0.5	22	V
Boost Voltage		-0.5	28	V
Boost to SW Voltage		-0.5	8	V
FB Voltage		-0.5	3	V
EN Voltage		-0.5	V <sub>IN</sub> + 0.3	V
Junction Temp	erature		150	°C
Soldering	Infrared/Convection Reflow (15sec)		220	°C
Information	Wave Soldering Lead temperature (10sec)		260	°C
T <sub>stg</sub>	Storage temperature	-65	150	°C

<sup>(1)</sup> If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/ Distributors for availability and specifications.

### 6.2 ESD Ratings

			VALUE	UNIT
V <sub>(ESD)</sub>	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins <sup>(1)</sup>	±2000	V

<sup>(1)</sup> JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

# 6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

	MIN	NOM MAX	UNIT
$V_{IN}$	3	18	V
SW Voltage	-0.5	18	V
Boost Voltage	-0.5	23	V
Boost to SW Voltage	1.6	5.5	V
Junction Temperature Range	-40	125	°C

### 6.4 Thermal Information

		LM2736	
	THERMAL METRIC <sup>(1)</sup>	DDC	UNIT
		6 PINS	
R <sub>0JA</sub> <sup>(2)</sup>	Junction-to-ambient thermal resistance	158.1	
R <sub>0</sub> JC(top)	Junction-to-case (top) thermal resistance	46.5	
$R_{\theta JB}$	Junction-to-board thermal resistance	29.5	°C/W
ΨЈТ	Junction-to-top characterization parameter	0.8	30/00
ΨЈВ	Junction-to-board characterization parameter	29.2	
R <sub>0JC(bot)</sub>	Junction-to-case (bottom) thermal resistance	n/a	

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, SPRA953.

Product Folder Links: LM2736

<sup>2)</sup> Thermal shutdown will occur if the junction temperature exceeds 165°C. The maximum power dissipation is a function of T<sub>J(MAX)</sub>, θ<sub>JA</sub> and T<sub>A</sub>. The maximum allowable power dissipation at any ambient temperature is P<sub>D</sub> = (T<sub>J(MAX)</sub> – T<sub>A</sub>)/θ<sub>JA</sub>. All numbers apply for packages soldered directly onto a 3" x 3" PC board with 2oz. copper on 4 layers in still air. For a 2 layer board using 1 oz. copper in still air, θ<sub>JA</sub> = 204°C/W.



### 6.5 Electrical Characteristics

Specifications with standard typeface are for  $T_J = 25^{\circ}\text{C}$  unless otherwise specified. Datasheet min/max specification limits are ensured by design, test, or statistical analysis.

	DADAMETED	TEST COMPITIONS	T <sub>J</sub> = 25°C		TJ = -40	°C to 125°C	UNIT
	PARAMETER	TEST CONDITIONS	MIN <sup>(1)</sup> TYP <sup>(2)</sup>	MAX <sup>(1)</sup>	MIN	TYP MAX	UNII
V <sub>FB</sub>	Feedback Voltage		1.250		1.225	1.275	V
$\Delta V_{FB}/\Delta V_{IN}$	Feedback Voltage Line Regulation	V <sub>IN</sub> = 3V to 18V	0.01				%/V
I <sub>FB</sub>	Feedback Input Bias Current	Sink/Source	10			250	nA
	Undervoltage Lockout	V <sub>IN</sub> Rising	2.74			2.90	
UVLO	Undervoltage Lockout	V <sub>IN</sub> Falling	2.3		2.0		V
	UVLO Hysteresis		0.44		0.30	0.62	
_	Outliebies Francisco	LM2736X	1.6		1.2	1.9	N 41 1
$F_{SW}$	Switching Frequency	LM2736Y	0.55		0.40	0.66	MHz
5	Maximum Duty Cycle	LM2736X	92%		85%		
$D_{MAX}$		LM2736Y	96%		90%		
_	Minimum Duty Cycle	LM2736X	2%				
D <sub>MIN</sub>		LM2736Y	1%				
R <sub>DS(ON)</sub>	Switch ON Resistance	V <sub>BOOST</sub> - V <sub>SW</sub> = 3V	350			650	mΩ
I <sub>CL</sub>	Switch Current Limit	V <sub>BOOST</sub> - V <sub>SW</sub> = 3V	1.5		1.0	2.3	Α
IQ	Quiescent Current	Switching	1.5			2.5	mA
	Quiescent Current (shutdown)	V <sub>EN</sub> = 0V	30				nA
		LM2736X (50% Duty Cycle)	2.2			3.3	A
I <sub>BOOST</sub>		LM2736Y (50% Duty Cycle)	0.9			1.6	- mA
V	Shutdown Threshold Voltage	V <sub>EN</sub> Falling				0.4	V
V <sub>EN_TH</sub>	Enable Threshold Voltage	V <sub>EN</sub> Rising			1.8		V
I <sub>EN</sub>	Enable Pin Current	Sink/Source	10				nA
I <sub>SW</sub>	Switch Leakage		40				nA

Specified to Texas Instruments' Average Outgoing Quality Level (AOQL).

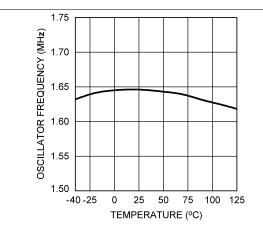
Product Folder Links: LM2736

Typicals represent the most likely parametric norm.



## 6.6 Typical Characteristics

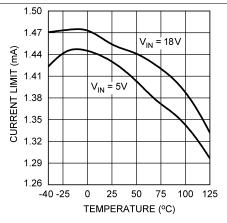
All curves taken at  $V_{IN}$  = 5V,  $V_{BOOST}$  -  $V_{SW}$  = 5V, L1 = 4.7  $\mu$ H ("X"), L1 = 10  $\mu$ H ("Y"), and  $T_A$  = 25°C, unless specified otherwise.



0.600 0.5000 0.500 0.500 0.500 0.500 0.500 0.500 0.500 0.500 0.5000 0.5

Figure 1. Oscillator Frequency vs Temperature - "X"

Figure 2. Oscillator Frequency vs Temperature - "Y"



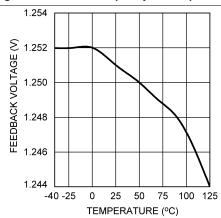
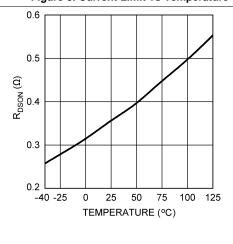


Figure 3. Current Limit vs Temperature

Figure 4. V<sub>FB</sub> vs Temperature



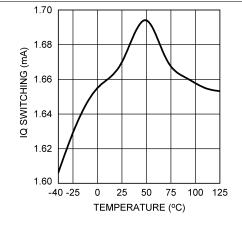


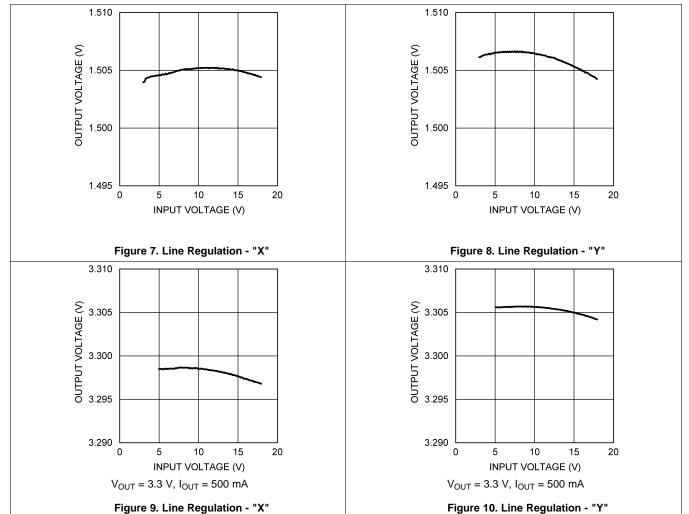
Figure 5. R<sub>DSON</sub> vs Temperature

Figure 6. IQ Switching vs Temperature



# **Typical Characteristics (continued)**

All curves taken at  $V_{IN}$  = 5V,  $V_{BOOST}$  -  $V_{SW}$  = 5V, L1 = 4.7  $\mu$ H ("X"), L1 = 10  $\mu$ H ("Y"), and  $T_A$  = 25°C, unless specified otherwise.





### 7 Detailed Description

#### 7.1 Overview

The LM2736 device is a constant frequency PWM buck regulator IC that delivers a 750 mA load current. The regulator has a preset switching frequency of either 550 kHz (LM2736Y) or 1.6 MHz (LM2736X). These high frequencies allow the LM2736 device to operate with small surface mount capacitors and inductors, resulting in DC/DC converters that require a minimum amount of board space. The LM2736 device is internally compensated, so it is simple to use, and requires few external components. The LM2736 device uses current-mode control to regulate the output voltage.

The following operating description of the LM2736 device will refer to the Simplified Block Diagram (*Functional Block Diagram*) and to the waveforms in Figure 11. The LM2736 device supplies a regulated output voltage by switching the internal NMOS control switch at constant frequency and variable duty cycle. A switching cycle begins at the falling edge of the reset pulse generated by the internal oscillator. When this pulse goes low, the output control logic turns on the internal NMOS control switch. During this on-time, the SW pin voltage ( $V_{SW}$ ) swings up to approximately  $V_{IN}$ , and the inductor current ( $I_L$ ) increases with a linear slope.  $I_L$  is measured by the current-sense amplifier, which generates an output proportional to the switch current. The sense signal is summed with the regulator's corrective ramp and compared to the error amplifier's output, which is proportional to the difference between the feedback voltage and  $V_{REF}$ . When the PWM comparator output goes high, the output switch turns off until the next switching cycle begins. During the switch off-time, inductor current discharges through Schottky diode D1, which forces the SW pin to swing below ground by the forward voltage ( $V_D$ ) of the catch diode. The regulator loop adjusts the duty cycle (D) to maintain a constant output voltage.

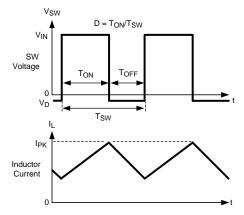


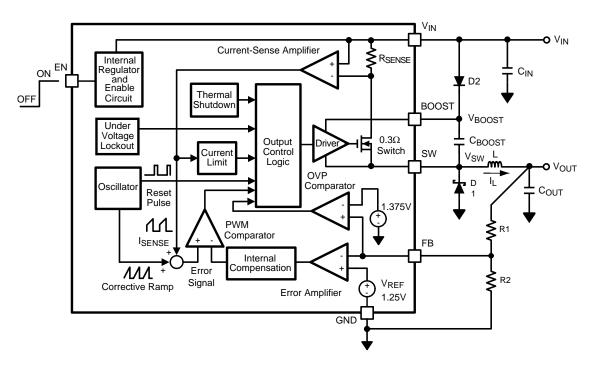
Figure 11. LM2736 Waveforms of SW Pin Voltage and Inductor Current

Submit Documentation Feedback

Copyright © 2004–2014, Texas Instruments Incorporated



### 7.2 Functional Block Diagram



### 7.3 Feature Description

### 7.3.1 Output Overvoltage Protection

The overvoltage comparator compares the FB pin voltage to a voltage that is 10% higher than the internal reference Vref. Once the FB pin voltage goes 10% above the internal reference, the internal NMOS control switch is turned off, which allows the output voltage to decrease toward regulation.

### 7.3.2 Undervoltage Lockout

Undervoltage lockout (UVLO) prevents the LM2736 device from operating until the input voltage exceeds 2.74 V (typ).

The UVLO threshold has approximately 440mV of hysteresis, so the part will operate until  $V_{IN}$  drops below 2.3 V (typ). Hysteresis prevents the part from turning off during power up if  $V_{IN}$  is non-monotonic.

### 7.3.3 Current Limit

The LM2736 device uses cycle-by-cycle current limiting to protect the output switch. During each switching cycle, a current limit comparator detects if the output switch current exceeds 1.5 A (typ), and turns off the switch until the next switching cycle begins.

#### 7.3.4 Thermal Shutdown

Thermal shutdown limits total power dissipation by turning off the output switch when the IC junction temperature exceeds 165°C. After thermal shutdown occurs, the output switch doesn't turn on until the junction temperature drops to approximately 150°C.



#### 7.4 Device Functional Modes

### 7.4.1 Enable Pin / Shutdown Mode

The LM2736 device has a shutdown mode that is controlled by the enable pin (EN). When a logic low voltage is applied to EN, the part is in shutdown mode and its quiescent current drops to typically 30 nA. Switch leakage adds another 40 nA from the input supply. The voltage at this pin should never exceed  $V_{IN} + 0.3 \text{ V}$ .

#### 7.4.2 Soft-Start

This function forces  $V_{OUT}$  to increase at a controlled rate during start up. During soft-start, the error amplifier's reference voltage ramps from 0 V to its nominal value of 1.25 V in approximately 200  $\mu$ s. This forces the regulator output to ramp up in a more linear and controlled fashion, which helps reduce inrush current.



# 8 Application and Implementation

#### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### 8.1 Application Information

#### 8.1.1 Boost Function

Capacitor  $C_{BOOST}$  and diode D2 in Figure 12 are used to generate a voltage  $V_{BOOST}$ .  $V_{BOOST}$  -  $V_{SW}$  is the gate drive voltage to the internal NMOS control switch. To properly drive the internal NMOS switch during its on-time,  $V_{BOOST}$  needs to be at least 1.6 V greater than  $V_{SW}$ . Although the LM2736 device will operate with this minimum voltage, it may not have sufficient gate drive to supply large values of output current. Therefore, it is recommended that  $V_{BOOST}$  be greater than 2.5 V above  $V_{SW}$  for best efficiency.  $V_{BOOST} - V_{SW}$  should not exceed the maximum operating limit of 5.5 V.

 $5.5 \text{ V} > \text{V}_{\text{BOOST}} - \text{V}_{\text{SW}} > 2.5 \text{ V}$  for best performance.

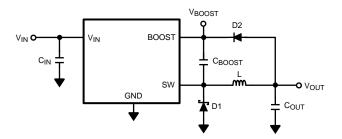


Figure 12. V<sub>OUT</sub> Charges C<sub>BOOST</sub>

When the LM2736 device starts up, internal circuitry from the BOOST pin supplies a maximum of 20 mA to  $C_{BOOST}$ . This current charges  $C_{BOOST}$  to a voltage sufficient to turn the switch on. The BOOST pin will continue to source current to  $C_{BOOST}$  until the voltage at the feedback pin is greater than 1.18 V.

There are various methods to derive V<sub>BOOST</sub>:

- 1. From the input voltage (V<sub>IN</sub>)
- 2. From the output voltage (V<sub>OUT</sub>)
- 3. From an external distributed voltage rail (V<sub>FXT</sub>)
- 4. From a shunt or series zener diode

In the *Functional Block Diagram*, capacitor  $C_{\mathsf{BOOST}}$  and diode D2 supply the gate-drive current for the NMOS switch. Capacitor  $C_{\mathsf{BOOST}}$  is charged via diode D2 by  $V_{\mathsf{IN}}$ . During a normal switching cycle, when the internal NMOS control switch is off ( $T_{\mathsf{OFF}}$ ) (refer to Figure 11),  $V_{\mathsf{BOOST}}$  equals  $V_{\mathsf{IN}}$  minus the forward voltage of D2 ( $V_{\mathsf{FD2}}$ ), during which the current in the inductor (L) forward biases the Schottky diode D1 ( $V_{\mathsf{FD1}}$ ). Therefore the voltage stored across  $C_{\mathsf{BOOST}}$  is

$$V_{BOOST} - V_{SW} = V_{IN} - V_{FD2} + V_{FD1}$$
 (1)

When the NMOS switch turns on (T<sub>ON</sub>), the switch pin rises to

$$V_{SW} = V_{IN} - (R_{DSON} \times I_L), \tag{2}$$

forcing V<sub>BOOST</sub> to rise thus reverse biasing D2. The voltage at V<sub>BOOST</sub> is then

$$V_{BOOST} = 2V_{IN} - (R_{DSON} \times I_L) - V_{FD2} + V_{FD1}$$
(3)

which is approximately

$$2 V_{\text{IN}} - 0.4 V$$
 (4)

for many applications. Thus the gate-drive voltage of the NMOS switch is approximately



## **Application Information (continued)**

$$V_{IN}$$
 - 0.2 V (5)

An alternate method for charging  $C_{BOOST}$  is to connect D2 to the output as shown in Figure 12. The output voltage should be between 2.5 V and 5.5 V, so that proper gate voltage will be applied to the internal switch. In this circuit,  $C_{BOOST}$  provides a gate drive voltage that is slightly less than  $V_{OUT}$ .

In applications where both  $V_{IN}$  and  $V_{OUT}$  are greater than 5.5 V, or less than 3 V,  $C_{BOOST}$  cannot be charged directly from these voltages. If  $V_{IN}$  and  $V_{OUT}$  are greater than 5.5 V,  $C_{BOOST}$  can be charged from  $V_{IN}$  or  $V_{OUT}$  minus a zener voltage by placing a zener diode D3 in series with D2, as shown in Figure 13. When using a series zener diode from the input, ensure that the regulation of the input supply doesn't create a voltage that falls outside the recommended  $V_{BOOST}$  voltage.

$$(V_{INMAX} - V_{D3}) < 5.5 \text{ V}$$
  
 $(V_{INMIN} - V_{D3}) > 1.6 \text{ V}$ 

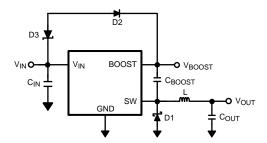


Figure 13. Zener Reduces Boost Voltage from VIN

An alternative method is to place the zener diode D3 in a shunt configuration as shown in Figure 14. A small 350 mW to 500 mW 5.1 V zener in a SOT or SOD package can be used for this purpose. A small ceramic capacitor such as a 6.3 V, 0.1  $\mu$ F capacitor (C4) should be placed in parallel with the zener diode. When the internal NMOS switch turns on, a pulse of current is drawn to charge the internal NMOS gate capacitance. The 0.1  $\mu$ F parallel shunt capacitor ensures that the V<sub>BOOST</sub> voltage is maintained during this time.

Resistor R3 should be chosen to provide enough RMS current to the zener diode (D3) and to the BOOST pin. A recommended choice for the zener current ( $I_{ZENER}$ ) is 1 mA. The current  $I_{BOOST}$  into the BOOST pin supplies the gate current of the NMOS control switch and varies typically according to the following formula for the X-version:

$$I_{BOOST} = 0.49 \text{ x (D + 0.54) x (V}_{ZENER} - V_{D2}) \text{ mA}$$
 (6)

I<sub>BOOST</sub> can be calculated for the Y version using the following:

$$I_{BOOST} = 0.20 \text{ x } (D + 0.54) \text{ x } (V_{ZENER} - V_{D2}) \mu A \tag{7}$$

where D is the duty cycle,  $V_{ZENER}$  and  $V_{D2}$  are in volts, and  $I_{BOOST}$  is in milliamps.  $V_{ZENER}$  is the voltage applied to the anode of the boost diode (D2), and  $V_{D2}$  is the average forward voltage across D2. Note that this formula for  $I_{BOOST}$  gives typical current. For the worst case  $I_{BOOST}$ , increase the current by 40%. In that case, the worst case boost current will be

$$I_{BOOST-MAX} = 1.4 \times I_{BOOST}$$
 (8)

R3 will then be given by

Submit Documentation Feedback

$$R3 = (V_{IN} - V_{ZENER}) / (1.4 \times I_{BOOST} + I_{ZENER})$$
(9)

For example, using the X-version let  $V_{IN}$  = 10 V,  $V_{ZENER}$  = 5 V,  $V_{D2}$  = 0.7 V,  $I_{ZENER}$  = 1 mA, and duty cycle D = 50%. Then

$$I_{BOOST} = 0.49 \times (0.5 + 0.54) \times (5 - 0.7) \text{ mA} = 2.19 \text{mA}$$
 (10)

$$R3 = (10 \text{ V} - 5 \text{ V}) / (1.4 \text{ x} 2.19 \text{ mA} + 1 \text{ mA}) = 1.23 \text{ k}\Omega$$
 (11)

Product Folder Links: LM2736



# **Application Information (continued)**

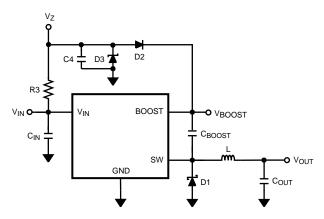


Figure 14. Boost Voltage Supplied from the Shunt Zener on  $V_{\rm IN}$ 

# 8.2 Typical Applications

# 8.2.1 LM2736X (1.6 MHz) $V_{BOOST}$ Derived from $V_{IN}$ 5 V to 1.5 V / 750 mA

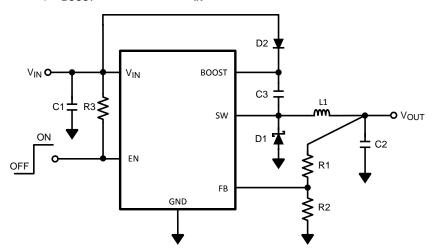


Figure 15. LM2736X (1.6 MHz)  $V_{BOOST}$  Derived from  $V_{IN}\,5$  V to 1.5 V / 750 mA

# 8.2.1.1 Design Requirements

Table 1. Bill of Materials for Figure 15

PART ID	PART VALUE	PART NUMBER	MANUFACTURER
U1	750 mA Buck Regulator	LM2736X	TI
C1, Input Cap	10-μF, 6.3V, X5R	C3216X5ROJ106M	TDK
C2, Output Cap	10-μF, 6.3V, X5R	C3216X5ROJ106M	TDK
C3, Boost Cap	0.01-uF, 16V, X7R	C1005X7R1C103K	TDK
D1, Catch Diode	0.3 V <sub>F</sub> Schottky 1 A, 10 VR	MBRM110L	ON Semi
D2, Boost Diode	1 V <sub>F</sub> @ 50 mA Diode	1N4148W	Diodes, Inc.
L1	4.7-µH, 1.7 A,	VLCF4020T- 4R7N1R2	TDK
R1	2 kΩ, 1%	CRCW06032001F	Vishay
R2	10 kΩ, 1%	CRCW06031002F	Vishay
R3	100 kΩ, 1%	CRCW06031003F	Vishay

Product Folder Links: LM2736



### 8.2.1.2 Detailed Design Procedures

#### 8.2.1.2.1 Inductor Selection

The Duty Cycle (D) can be approximated quickly using the ratio of output voltage ( $V_O$ ) to input voltage ( $V_{IN}$ ) as shown in Equation 12:

$$D = \frac{V_O}{V_{IN}} \tag{12}$$

The catch diode (D1) forward voltage drop and the voltage drop across the internal NMOS must be included to calculate a more accurate duty cycle. Use Equation 13 to Calculate D.

$$D = \frac{V_O + V_D}{V_{IN} + V_D - V_{SW}}$$
(13)

V<sub>SW</sub> can be approximated by:

$$V_{SW} = I_O \times R_{DS(ON)} \tag{14}$$

The diode forward drop  $(V_D)$  can range from 0.3 V to 0.7 V depending on the quality of the diode. The lower  $V_D$  is, the higher the operating efficiency of the converter.

The inductor value determines the output ripple current. Lower inductor values decrease the size of the inductor, but increase the output ripple current. An increase in the inductor value will decrease the output ripple current. The ratio of ripple current ( $\Delta I_{\rm L}$ ) to output current ( $I_{\rm C}$ ) is optimized when it is set between 0.3 and 0.4 at 750 mA. The ratio r is defined in .

$$r = \frac{\Delta i_L}{I_O} \tag{15}$$

One must also ensure that the minimum current limit (1.0 A) is not exceeded, so the peak current in the inductor must be calculated. Use Equation 16 to calculate the peak current (I<sub>I PK</sub>) in the inductor.

$$I_{\rm I,PK} = I_{\rm O} + \Delta I_{\rm I}/2 \tag{16}$$

If r = 0.7 at an output of 750 mA, the peak current in the inductor will be 1.0125 A. The minimum ensured current limit over all operating conditions is 1.0 A. One can either reduce r to 0.6 resulting in a 975 mA peak current, or make the engineering judgement that 12.5 mA over will be safe enough with a 1.5 A typical current limit and 6 sigma limits. When the designed maximum output current is reduced, the ratio r can be increased. At a current of 0.1 A, r can be made as high as 0.9. The ripple ratio can be increased at lighter loads because the net ripple is actually quite low, and if r remains constant the inductor value can be made quite large. Equation 17 is empirically developed for the maximum ripple ratio at any current below 2 A.

$$r = 0.387 \times I_{OII}^{-0.3667}$$
 (17)

Note that this is just a guideline.

The LM2736 device operates at frequencies allowing the use of ceramic output capacitors without compromising transient response. Ceramic capacitors allow higher inductor ripple without significantly increasing output ripple. See the *Output Capacitor* section for more details on calculating output voltage ripple.

Now that the ripple current or ripple ratio is determined, the inductance is calculated using Equation 18

$$L = \frac{V_{O} + V_{D}}{I_{O} \times r \times f_{S}} \times (1-D)$$
 (18)

where  $f_s$  is the switching frequency and  $I_O$  is the output current. When selecting an inductor, make sure that it is capable of supporting the peak output current without saturating. Inductor saturation will result in a sudden reduction in inductance and prevent the regulator from operating correctly. Because of the speed of the internal current limit, the peak current of the inductor need only be specified for the required maximum output current. For example, if the designed maximum output current is 0.5 A and the peak current is 0.7 A, then the inductor should



be specified with a saturation current limit of >0.7 A. There is no need to specify the saturation or peak current of the inductor at the 1.5 A typical switch current limit. The difference in inductor size is a factor of 5. Because of the operating frequency of the LM2736, ferrite based inductors are preferred to minimize core losses. This presents little restriction since the variety of ferrite based inductors is huge. Lastly, inductors with lower series resistance (DCR) will provide better operating efficiency. For recommended inductors see Example Circuits.

#### 8.2.1.2.2 Input Capacitor

An input capacitor is necessary to ensure that  $V_{IN}$  does not drop excessively during switching transients. The primary specifications of the input capacitor are capacitance, voltage, RMS current rating, and ESL (Equivalent Series Inductance). The recommended input capacitance is 10- $\mu$ F, although 4.7- $\mu$ F works well for input voltages below 6 V. The input voltage rating is specifically stated by the capacitor manufacturer. Make sure to check any recommended deratings and also verify if there is any significant change in capacitance at the operating input voltage and the operating temperature. The input capacitor maximum RMS input current rating (I<sub>RMS-IN</sub>) must be greater than:

$$I_{RMS-IN} = I_O \times \sqrt{D \times \left(1 - D + \frac{r^2}{12}\right)}$$
 (19)

It can be shown from the above equation that maximum RMS capacitor current occurs when D = 0.5. Always calculate the RMS at the point where the duty cycle, D, is closest to 0.5. The ESL of an input capacitor is usually determined by the effective cross sectional area of the current path. A large leaded capacitor will have high ESL and a 0805 ceramic chip capacitor will have very low ESL. At the operating frequencies of the LM2736, certain capacitors may have an ESL so large that the resulting impedance ( $2\pi fL$ ) will be higher than that required to provide stable operation. As a result, surface mount capacitors are strongly recommended. Sanyo POSCAP, Tantalum or Niobium, Panasonic SP or Cornell Dubilier ESR, and multilayer ceramic capacitors (MLCC) are all good choices for both input and output capacitors and have very low ESL. For MLCCs it is recommended to use X7R or X5R dielectrics. Consult capacitor manufacturer datasheet to see how rated capacitance varies over operating conditions.

#### 8.2.1.2.3 Output Capacitor

The output capacitor is selected based upon the desired output ripple and transient response. The initial current of a load transient is provided mainly by the output capacitor. The output ripple of the converter is:

$$\Delta V_{O} = \Delta i_{L} \times (R_{ESR} + \frac{1}{8 \times f_{S} \times C_{O}})$$
(20)

When using MLCCs, the ESR is typically so low that the capacitive ripple may dominate. When this occurs, the output ripple will be approximately sinusoidal and 90° phase shifted from the switching action. Given the availability and quality of MLCCs and the expected output voltage of designs using the LM2736, there is really no need to review any other capacitor technologies. Another benefit of ceramic capacitors is their ability to bypass high frequency noise. A certain amount of switching edge noise will couple through parasitic capacitances in the inductor to the output. A ceramic capacitor will bypass this noise while a tantalum will not. Since the output capacitor is one of the two external components that control the stability of the regulator control loop, most applications will require a minimum at 10-µF of output capacitance. Capacitance can be increased significantly with little detriment to the regulator stability. Like the input capacitor, recommended multilayer ceramic capacitors are X7R or X5R. Again, verify actual capacitance at the desired operating voltage and temperature.

Check the RMS current rating of the capacitor. The RMS current rating of the capacitor chosen must also meet the following condition:

$$I_{RMS-OUT} = I_O x \frac{r}{\sqrt{12}}$$
 (21)

#### 8.2.1.2.4 Catch Diode

The catch diode (D1) conducts during the switch off-time. A Schottky diode is recommended for its fast switching times and low forward voltage drop. The catch diode should be chosen so that its current rating is greater than:

$$I_{D1} = I_{O} \times (1-D)$$
 (22)

The reverse breakdown rating of the diode must be at least the maximum input voltage plus appropriate margin. To improve efficiency choose a Schottky diode with a low forward voltage drop.

Copyright © 2004–2014, Texas Instruments Incorporated



#### 8.2.1.2.5 Boost Diode

A standard diode such as the 1N4148 type is recommended. For  $V_{BOOST}$  circuits derived from voltages less than 3.3 V, a small-signal Schottky diode is recommended for greater efficiency. A good choice is the BAT54 small signal diode.

#### 8.2.1.2.6 Boost Capacitor

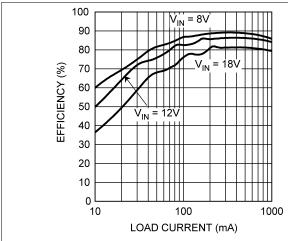
A ceramic  $0.01-\mu F$  capacitor with a voltage rating of at least 16 V is sufficient. The X7R and X5R MLCCs provide the best performance.

### 8.2.1.2.7 Output Voltage

The output voltage is set using the following equation where R2 is connected between the FB pin and GND, and R1 is connected between  $V_O$  and the FB pin. A good value for R2 is 10 k $\Omega$ .

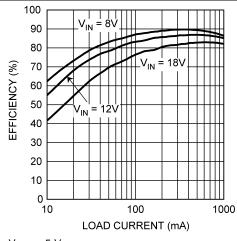
$$R1 = \left(\frac{V_O}{V_{REF}} - 1\right) \times R2 \tag{23}$$

### 8.2.1.3 Application Curves



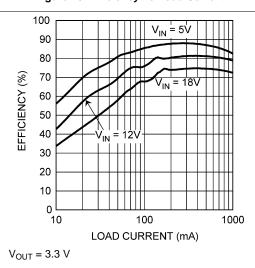
 $V_{OUT} = 5 V$ 

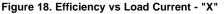
Figure 16. Efficiency vs Load Current - "X"

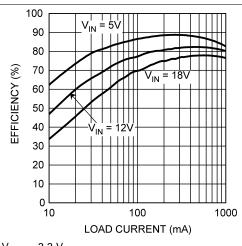


 $V_{OUT} = 5 V$ 

Figure 17. Efficiency vs Load Current - "Y"







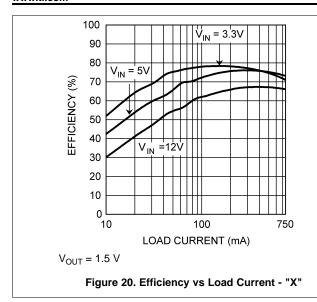
 $V_{OUT} = 3.3 V$ 

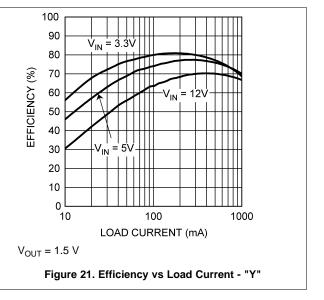
Figure 19. Efficiency vs Load Current - "Y"

Submit Documentation Feedback

Copyright © 2004–2014, Texas Instruments Incorporated









# 8.2.2 LM2736X (1.6 MHz) $V_{BOOST}$ Derived from $V_{OUT}$ 12 V to 3.3 V / 750 mA

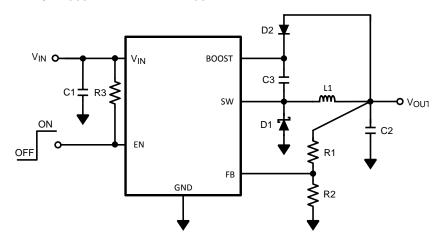


Figure 22. LM2736X (1.6 MHz)  $V_{BOOST}$  Derived from  $V_{OUT}$  12 V to 3.3 V / 750 mA

# 8.2.2.1 Design Requirements

Table 2. Bill of Materials for Figure 22

PART ID	PART VALUE	PART NUMBER	MANUFACTURER
U1	750mA Buck Regulator	LM2736X	TI
C1, Input Cap	10μF, 25V, X7R	C3225X7R1E106M	TDK
C2, Output Cap	22μF, 6.3V, X5R	C3216X5ROJ226M	TDK
C3, Boost Cap	0.01µF, 16V, X7R	C1005X7R1C103K	TDK
D1, Catch Diode	0.34V <sub>F</sub> Schottky 1A, 30VR	SS1P3L	Vishay
D2, Boost Diode	30V, 200 mA Schottky	BAT54	Diodes Inc.
L1	4.7μH, 1.7A,	VLCF4020T- 4R7N1R2	TDK
R1	16.5kΩ, 1%	CRCW06031652F	Vishay
R2	10.0 kΩ, 1%	CRCW06031002F	Vishay
R3	100kΩ, 1%	CRCW06031003F	Vishay

### 8.2.2.2 Detailed Design Procedures

Please refer to Detailed Design Procedures.

### 8.2.2.3 Application Curves

Please refer to Application Curves



# 8.2.3 LM2736X (1.6 MHz) $V_{BOOST}$ Derived from $V_{SHUNT}$ 18 V to 1.5 V / 750 mA

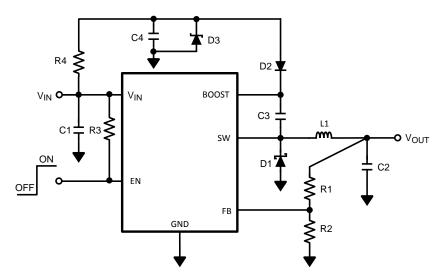


Figure 23. LM2736X (1.6 MHz)  $V_{BOOST}$  Derived from  $V_{SHUNT}$  18 V to 1.5 V / 750 mA

### 8.2.3.1 Design Requirements

Table 3. Bill of Materials for Figure 23

PART ID	PART VALUE	PART NUMBER	MANUFACTURER
U1	750mA Buck Regulator	LM2736X	TI
C1, Input Cap	10μF, 25V, X7R	C3225X7R1E106M	TDK
C2, Output Cap	22μF, 6.3V, X5R	C3216X5ROJ226M	TDK
C3, Boost Cap	0.01µF, 16V, X7R	C1005X7R1C103K	TDK
C4, Shunt Cap	0.1µF, 6.3V, X5R	C1005X5R0J104K	TDK
D1, Catch Diode	0.4V <sub>F</sub> Schottky 1A, 30VR	SS1P3L	Vishay
D2, Boost Diode	1V <sub>F</sub> @ 50mA Diode	1N4148W	Diodes, Inc.
D3, Zener Diode	5.1V 250Mw SOT	BZX84C5V1	Vishay
L1	6.8µH, 1.6A,	SLF7032T-6R8M1R6	TDK
R1	2kΩ, 1%	CRCW06032001F	Vishay
R2	10kΩ, 1%	CRCW06031002F	Vishay
R3	100kΩ, 1%	CRCW06031003F	Vishay
R4	4.12kΩ, 1%	CRCW06034121F	Vishay

Product Folder Links: LM2736

### 8.2.3.2 Detailed Design Procedure

Please refer to Detailed Design Procedures.

# 8.2.3.3 Application Curves

Please refer to Application Curves.

# TEXAS INSTRUMENTS

# 8.2.4 LM2736X (1.6 MHz) $V_{BOOST}$ Derived from Series Zener Diode ( $V_{IN}$ ) 15 V to 1.5 V / 750 mA

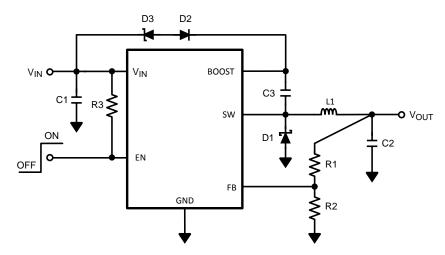


Figure 24. LM2736X (1.6 MHz)  $V_{BOOST}$  Derived from Series Zener Diode ( $V_{IN}$ ) 15 V to 1.5 V / 750 mA

# 8.2.4.1 Design Requirements

Table 4. Bill of Materials for Figure 24

		•	
PART ID	PART VALUE	PART NUMBER	MANUFACTURER
U1	750 mA Buck Regulator	LM2736X	TI
C1, Input Cap	10-μF, 25 V, X7R	C3225X7R1E106M	TDK
C2, Output Cap	22-μF, 6.3 V, X5R	C3216X5ROJ226M	TDK
C3, Boost Cap	0.01-µF, 16 V, X7R	C1005X7R1C103K	TDK
D1, Catch Diode	0.4 V <sub>F</sub> Schottky 1 A, 30VR	SS1P3L	Vishay
D2, Boost Diode	1V <sub>F</sub> @ 50 mA Diode	1N4148W	Diodes, Inc.
D3, Zener Diode	11 V 350 Mw SOT	BZX84C11T	Diodes, Inc.
L1	6.8μH, 1.6 A,	SLF7032T-6R8M1R6	TDK
R1	2 kΩ, 1%	CRCW06032001F	Vishay
R2	10 kΩ, 1%	CRCW06031002F	Vishay
R3	100 kΩ, 1%	CRCW06031003F	Vishay

### 8.2.4.2 Detailed Design Procedure

Please refer to Detailed Design Procedures.

### 8.2.4.3 Application Curves

Please refer to Application Curves



# 8.2.5 LM2736X (1.6 MHz) V<sub>BOOST</sub> Derived from Series Zener Diode (V<sub>OUT</sub>) 15 V to 9 V / 750 mA

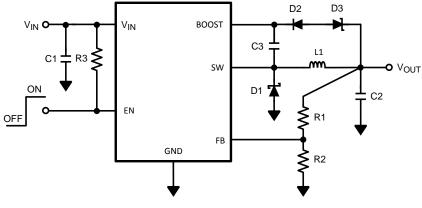


Figure 25.

### 8.2.5.1 Design Requirements

Table 5. Bill of Materials for Figure 25

, and of 2 in or materials 10. 1 igns 20									
PART ID	PART VALUE	PART NUMBER	MANUFACTURER						
U1	750mA Buck Regulator	LM2736X	TI						
C1, Input Cap	10μF, 25V, X7R	C3225X7R1E106M	TDK						
C2, Output Cap	22μF, 16V, X5R	C3216X5R1C226M	TDK						
C3, Boost Cap	0.01μF, 16V, X7R	C1005X7R1C103K	TDK						
D1, Catch Diode	0.4V <sub>F</sub> Schottky 1A, 30VR	SS1P3L	Vishay						
D2, Boost Diode	1V <sub>F</sub> @ 50mA Diode	1N4148W	Diodes, Inc.						
D3, Zener Diode	4.3V 350mw SOT	BZX84C4V3	Diodes, Inc.						
L1	6.8µH, 1.6A,	SLF7032T-6R8M1R6	TDK						
R1	61.9kΩ, 1%	CRCW06036192F	Vishay						
R2	10kΩ, 1%	CRCW06031002F	Vishay						
R3	100kΩ, 1%	CRCW06031003F	Vishay						

### 8.2.5.2 Detailed Design Procedure

Please refer to *Detailed Design Procedures*.

### 8.2.5.3 Application Curves

Please refer to Application Curves

# 8.2.6 LM2736Y (550 kHz) $V_{BOOST}$ Derived from $V_{IN}\,5$ V to 1.5 V / 750 mA

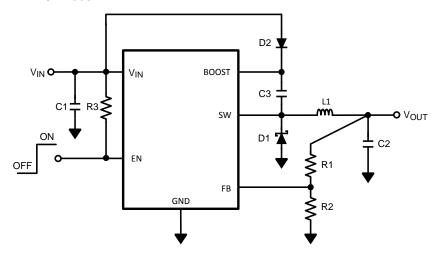


Figure 26. LM2736Y (550 kHz)  $V_{BOOST}$  Derived from  $V_{IN}\,5$  V to 1.5 V / 750 mA

### 8.2.6.1 Design Requirements

Table 6. Bill of Materials for Figure 26

PART ID	PART VALUE	PART NUMBER	MANUFACTURER		
U1	750mA Buck Regulator	LM2736Y	TI		
C1, Input Cap	10μF, 6.3V, X5R	C3216X5ROJ106M	TDK		
C2, Output Cap	22μF, 6.3V, X5R	C3216X5ROJ226M	TDK		
C3, Boost Cap	0.01μF, 16V, X7R	C1005X7R1C103K	TDK		
D1, Catch Diode	0.3V <sub>F</sub> Schottky 1A, 10VR	MBRM110L	ON Semi		
D2, Boost Diode	1V <sub>F</sub> @ 50mA Diode	1N4148W	Diodes, Inc.		
L1	10μH, 1.6A,	SLF7032T-100M1R4	TDK		
R1	2kΩ, 1%	CRCW06032001F	Vishay		
R2	10kΩ, 1%	CRCW06031002F	Vishay		
R3	100kΩ, 1%	CRCW06031003F	Vishay		

### 8.2.6.2 Detailed Design Procedure

Please refer to Detailed Design Procedures.

### 8.2.6.3 Application Curves

Please refer to Application Curves.



# 8.2.7 LM2736Y (550 kHz) $V_{BOOST}$ Derived from $V_{OUT}$ 12 V to 3.3 V / 750 mA

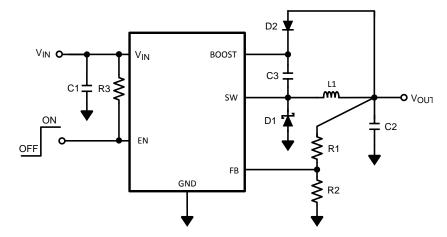


Figure 27. LM2736Y (550 kHz)  $V_{BOOST}$  Derived from  $V_{OUT}$  12 V to 3.3 V / 750 mA

# 8.2.7.1 Design Requirements

Table 7. Bill of Materials for Figure 27

PART ID	PART VALUE	PART NUMBER	MANUFACTURER
U1	750mA Buck Regulator	LM2736Y	TI
C1, Input Cap	10μF, 25V, X7R	C3225X7R1E106M	TDK
C2, Output Cap	22μF, 6.3V, X5R	C3216X5ROJ226M	TDK
C3, Boost Cap	0.01µF, 16V, X7R	C1005X7R1C103K	TDK
D1, Catch Diode	0.34V <sub>F</sub> Schottky 1A, 30VR	SS1P3L	Vishay
D2, Boost Diode	30V, 200 mA Schottky	BAT54	Diodes Inc.
L1	10μH, 1.6A,	SLF7032T-100M1R4	TDK
R1	16.5kΩ, 1%	CRCW06031652F	Vishay
R2	10.0 kΩ, 1%	CRCW06031002F	Vishay
R3	100kΩ, 1%	CRCW06031003F	Vishay

### 8.2.7.2 Detailed Design Procedure

Please refer to Detailed Design Procedures.

### 8.2.7.3 Application Curves

Please refer to Application Curves.

Copyright © 2004–2014, Texas Instruments Incorporated

# 8.2.8 LM2736Y (550 kHz) $V_{BOOST}$ Derived from $V_{SHUNT}$ 18 V to 1.5 V / 750 mA

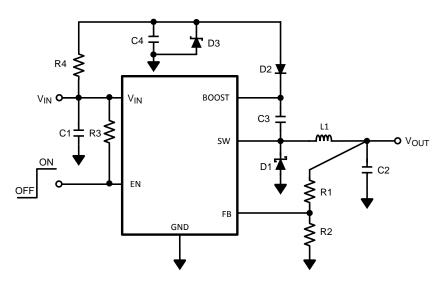


Figure 28. LM2736Y (550 kHz)  $V_{BOOST}$  Derived from  $V_{SHUNT}$  18 V to 1.5 V / 750 mA

### 8.2.8.1 Design Requirements

Table 8. Bill of Materials for Figure 28

PART ID	PART VALUE	PART NUMBER	MANUFACTURER
U1	750mA Buck Regulator	LM2736Y	TI
C1, Input Cap	10μF, 25V, X7R	C3225X7R1E106M	TDK
C2, Output Cap	22μF, 6.3V, X5R	C3216X5ROJ226M	TDK
C3, Boost Cap	0.01μF, 16V, X7R	C1005X7R1C103K	TDK
C4, Shunt Cap	0.1μF, 6.3V, X5R	C1005X5R0J104K	TDK
D1, Catch Diode	0.4V <sub>F</sub> Schottky 1A, 30VR	SS1P3L	Vishay
D2, Boost Diode	1V <sub>F</sub> @ 50mA Diode	1N4148W	Diodes, Inc.
D3, Zener Diode	5.1V 250Mw SOT	BZX84C5V1	Vishay
L1	15μH, 1.5A	SLF7045T-150M1R5	TDK
R1	2kΩ, 1%	CRCW06032001F	Vishay
R2	10kΩ, 1%	CRCW06031002F	Vishay
R3	100kΩ, 1%	CRCW06031003F	Vishay
R4	4.12kΩ, 1%	CRCW06034121F	Vishay

### 8.2.8.2 Detailed Design Procedure

Please refer to Detailed Design Procedures.

# 8.2.8.3 Application Curves

Please refer to Application Curves.



# 8.2.9 LM2736Y (550 kHz) $V_{BOOST}$ Derived from Series Zener Diode ( $V_{IN}$ ) 15 V to 1.5 V / 750 mA

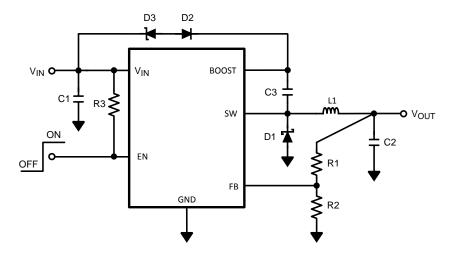


Figure 29. M2736Y (550 kHz)  $V_{BOOST}$  Derived from Series Zener Diode ( $V_{IN}$ ) 15 V to 1.5 V / 750 mA

# 8.2.9.1 Design Requirements

Table 9. Bill of Materials for Figure 29

PART ID	PART VALUE	PART NUMBER	MANUFACTURER						
U1	750mA Buck Regulator	LM2736Y	TI						
C1, Input Cap	10μF, 25V, X7R	C3225X7R1E106M	TDK						
C2, Output Cap	22μF, 6.3V, X5R	C3216X5ROJ226M	TDK						
C3, Boost Cap	0.01μF, 16V, X7R	C1005X7R1C103K	TDK						
D1, Catch Diode	0.4V <sub>F</sub> Schottky 1A, 30VR	SS1P3L	Vishay						
D2, Boost Diode	1V <sub>F</sub> @ 50mA Diode	1N4148W	Diodes, Inc.						
D3, Zener Diode	11V 350Mw SOT	BZX84C11T	Diodes, Inc.						
L1	15μH, 1.5A,	SLF7045T-150M1R5	TDK						
R1	2kΩ, 1%	CRCW06032001F	Vishay						
R2	10kΩ, 1%	CRCW06031002F	Vishay						
R3	100kΩ, 1%	CRCW06031003F	Vishay						

### 8.2.9.2 Detailed Design Procedure

Please refer to Detailed Design Procedures.

### 8.2.9.3 Application Curves

Please refer to Application Curves.

### 8.2.10 LM2736Y (550 kHz) V<sub>BOOST</sub> Derived from Series Zener Diode (V<sub>OUT</sub>) 15 V to 9 V / 750 mA

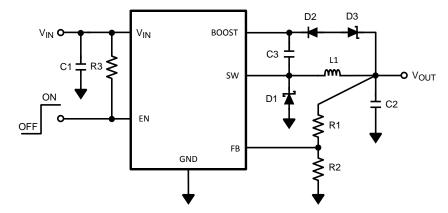


Figure 30. LM2736Y (550 kHz) V<sub>BOOST</sub> Derived from Series Zener Diode (V<sub>OUT</sub>) 15 V to 9 V / 750 mA

### 8.2.10.1 Design Requirements

Table 10. Bill of Materials for Figure 30

PART ID	PART VALUE	PART NUMBER	MANUFACTURER
U1	750 mA Buck Regulator	LM2736Y	TI
C1, Input Cap	10-μF, 25 V, X7R	C3225X7R1E106M	TDK
C2, Output Cap	22-μF, 16 V, X5R	C3216X5R1C226M	TDK
C3, Boost Cap	0.01-μF, 16 V, X7R	C1005X7R1C103K	TDK
D1, Catch Diode	0.4 V <sub>F</sub> Schottky 1 A, 30 VR	SS1P3L	Vishay
D2, Boost Diode	1 V <sub>F</sub> @ 50 mA Diode	1N4148W	Diodes, Inc.
D3, Zener Diode	4.3 V 350 mw SOT	BZX84C4V3	Diodes, Inc.
L1	22 μH, 1.4 A,	SLF7045T-220M1R3-1PF	TDK
R1	61.9 kΩ, 1%	CRCW06036192F	Vishay
R2	10 kΩ, 1%	CRCW06031002F	Vishay
R3	100 kΩ, 1%	CRCW06031003F	Vishay

### 8.2.10.2 Detailed Design Procedure

Please refer to Detailed Design Procedures.

# 8.2.10.3 Application Curves

Please refer to Application Curves.

### 9 Power Supply Recommendations

Input voltage is rated as 3 V to 18 V however care should be taken in certain circuit configurations eg.  $V_{BOOST}$  derived from  $V_{IN}$  where the requirement that  $V_{BOOST}$  -  $V_{SW}$  < 5.5 V should be observed. Also for best efficiency  $V_{BOOST}$  should be at least 2.5 V above  $V_{SW}$ .

The voltage on the Enable pin should not exceed  $V_{\text{IN}}$  by more than 0.3 V.



## 10 Layout

### 10.1 Layout Guidelines

When planning layout there are a few things to consider when trying to achieve a clean, regulated output. The most important consideration when completing the layout is the close coupling of the GND connections of the  $C_{\text{IN}}$  capacitor and the catch diode D1. These ground ends should be close to one another and be connected to the GND plane with at least two through-holes. Place these components as close to the IC as possible. Next in importance is the location of the GND connection of the  $C_{\text{OUT}}$  capacitor, which should be near the GND connections of  $C_{\text{IN}}$  and D1.

There should be a continuous ground plane on the bottom layer of a two-layer board except under the switching node island.

The FB pin is a high impedance node and care should be taken to make the FB trace short to avoid noise pickup and inaccurate regulation. The feedback resistors should be placed as close as possible to the IC, with the GND of R2 placed as close as possible to the GND of the IC. The V<sub>OUT</sub> trace to R1 should be routed away from the inductor and any other traces that are switching.

High AC currents flow through the  $V_{IN}$ , SW and  $V_{OUT}$  traces, so they should be as short and wide as possible. However, making the traces wide increases radiated noise, so the designer must make this trade-off. Radiated noise can be decreased by choosing a shielded inductor.

The remaining components should also be placed as close as possible to the IC. Please see Application Note AN-1229 SNVA054 for further considerations and the LM2736 device demo board as an example of a four-layer layout.



# 10.2 Layout Example

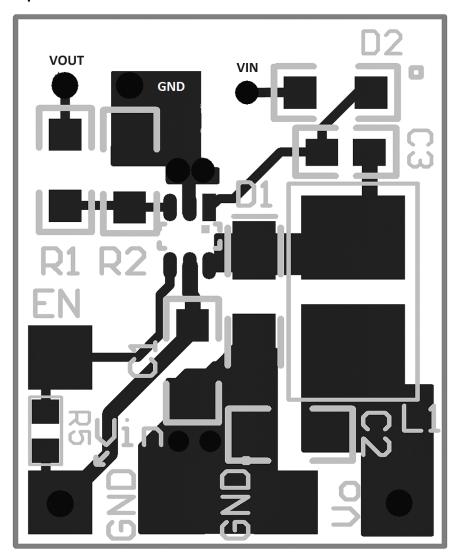


Figure 31. Top Layer

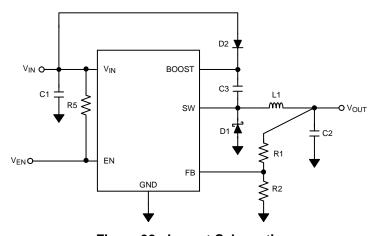


Figure 32. Layout Schematic



# 11 Device and Documentation Support

### 11.1 Device Support

### 11.1.1 Third-Party Products Disclaimer

TI'S PUBLICATION OF INFORMATION REGARDING THIRD-PARTY PRODUCTS OR SERVICES DOES NOT CONSTITUTE AN ENDORSEMENT REGARDING THE SUITABILITY OF SUCH PRODUCTS OR SERVICES OR A WARRANTY, REPRESENTATION OR ENDORSEMENT OF SUCH PRODUCTS OR SERVICES, EITHER ALONE OR IN COMBINATION WITH ANY TI PRODUCT OR SERVICE.

# 11.2 Documentation Support

#### 11.2.1 Related Documentation

For related documentation see the following:

AN-1229 SIMPLE SWITCHER® PCB Layout Guidelines SNVA054

### 11.3 Trademarks

WEBENCH is a registered trademark of Texas Instruments. All other trademarks are the property of their respective owners.

### 11.4 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

# 11.5 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

Product Folder Links: LM2736



# 12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.





16-Oct-2014

#### **PACKAGING INFORMATION**

Orderable Device	Status	Package Type	_		_	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
	(1)		Drawing		Qty	(2)	(6)	(3)		(4/5)	
LM2736XMK	NRND	SOT	DDC	6	1000	TBD	Call TI	Call TI	-40 to 125	SHAB	
LM2736XMK/NOPB	ACTIVE	SOT	DDC	6	1000	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	SHAB	Samples
LM2736XMKX/NOPB	ACTIVE	SOT	DDC	6	3000	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	SHAB	Samples
LM2736YMK	NRND	SOT	DDC	6	1000	TBD	Call TI	Call TI	-40 to 125	SHBB	
LM2736YMK/NOPB	ACTIVE	SOT	DDC	6	1000	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	SHBB	Samples
LM2736YMKX/NOPB	ACTIVE	SOT	DDC	6	3000	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	SHBB	Samples

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.



# **PACKAGE OPTION ADDENDUM**

16-Oct-2014

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

**Important Information and Disclaimer:** The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

# PACKAGE MATERIALS INFORMATION

www.ti.com 16-Oct-2014

# TAPE AND REEL INFORMATION





Α0	Dimension designed to accommodate the component width
	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



### \*All dimensions are nominal

Device		Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LM2736XMK	SOT	DDC	6	1000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LM2736XMK/NOPB	SOT	DDC	6	1000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LM2736XMKX/NOPB	SOT	DDC	6	3000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LM2736YMK	SOT	DDC	6	1000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LM2736YMK/NOPB	SOT	DDC	6	1000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LM2736YMKX/NOPB	SOT	DDC	6	3000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3

www.ti.com 16-Oct-2014



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LM2736XMK	SOT	DDC	6	1000	210.0	185.0	35.0
LM2736XMK/NOPB	SOT	DDC	6	1000	210.0	185.0	35.0
LM2736XMKX/NOPB	SOT	DDC	6	3000	210.0	185.0	35.0
LM2736YMK	SOT	DDC	6	1000	210.0	185.0	35.0
LM2736YMK/NOPB	SOT	DDC	6	1000	210.0	185.0	35.0
LM2736YMKX/NOPB	SOT	DDC	6	3000	210.0	185.0	35.0

#### IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, enhancements, improvements and other changes to its semiconductor products and services per JESD46, latest issue, and to discontinue any product or service per JESD48, latest issue. Buyers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All semiconductor products (also referred to herein as "components") are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its components to the specifications applicable at the time of sale, in accordance with the warranty in TI's terms and conditions of sale of semiconductor products. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by applicable law, testing of all parameters of each component is not necessarily performed.

TI assumes no liability for applications assistance or the design of Buyers' products. Buyers are responsible for their products and applications using TI components. To minimize the risks associated with Buyers' products and applications, Buyers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right relating to any combination, machine, or process in which TI components or services are used. Information published by TI regarding third-party products or services does not constitute a license to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of significant portions of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI components or services with statements different from or beyond the parameters stated by TI for that component or service voids all express and any implied warranties for the associated TI component or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Buyer acknowledges and agrees that it is solely responsible for compliance with all legal, regulatory and safety-related requirements concerning its products, and any use of TI components in its applications, notwithstanding any applications-related information or support that may be provided by TI. Buyer represents and agrees that it has all the necessary expertise to create and implement safeguards which anticipate dangerous consequences of failures, monitor failures and their consequences, lessen the likelihood of failures that might cause harm and take appropriate remedial actions. Buyer will fully indemnify TI and its representatives against any damages arising out of the use of any TI components in safety-critical applications.

In some cases, TI components may be promoted specifically to facilitate safety-related applications. With such components, TI's goal is to help enable customers to design and create their own end-product solutions that meet applicable functional safety standards and requirements. Nonetheless, such components are subject to these terms.

No TI components are authorized for use in FDA Class III (or similar life-critical medical equipment) unless authorized officers of the parties have executed a special agreement specifically governing such use.

Only those TI components which TI has specifically designated as military grade or "enhanced plastic" are designed and intended for use in military/aerospace applications or environments. Buyer acknowledges and agrees that any military or aerospace use of TI components which have *not* been so designated is solely at the Buyer's risk, and that Buyer is solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI has specifically designated certain components as meeting ISO/TS16949 requirements, mainly for automotive use. In any case of use of non-designated products, TI will not be responsible for any failure to meet ISO/TS16949.

### Products Applications

Audio www.ti.com/audio Automotive and Transportation www.ti.com/automotive Communications and Telecom Amplifiers amplifier.ti.com www.ti.com/communications **Data Converters** dataconverter.ti.com Computers and Peripherals www.ti.com/computers **DLP® Products** www.dlp.com Consumer Electronics www.ti.com/consumer-apps

DSP **Energy and Lighting** dsp.ti.com www.ti.com/energy Clocks and Timers www.ti.com/clocks Industrial www.ti.com/industrial Interface interface.ti.com Medical www.ti.com/medical logic.ti.com Logic Security www.ti.com/security

Power Mgmt power.ti.com Space, Avionics and Defense www.ti.com/space-avionics-defense

Microcontrollers <u>microcontroller.ti.com</u> Video and Imaging <u>www.ti.com/video</u>

RFID <u>www.ti-rfid.com</u>

OMAP Applications Processors <u>www.ti.com/omap</u> TI E2E Community <u>e2e.ti.com</u>

Wireless Connectivity <u>www.ti.com/wirelessconnectivity</u>